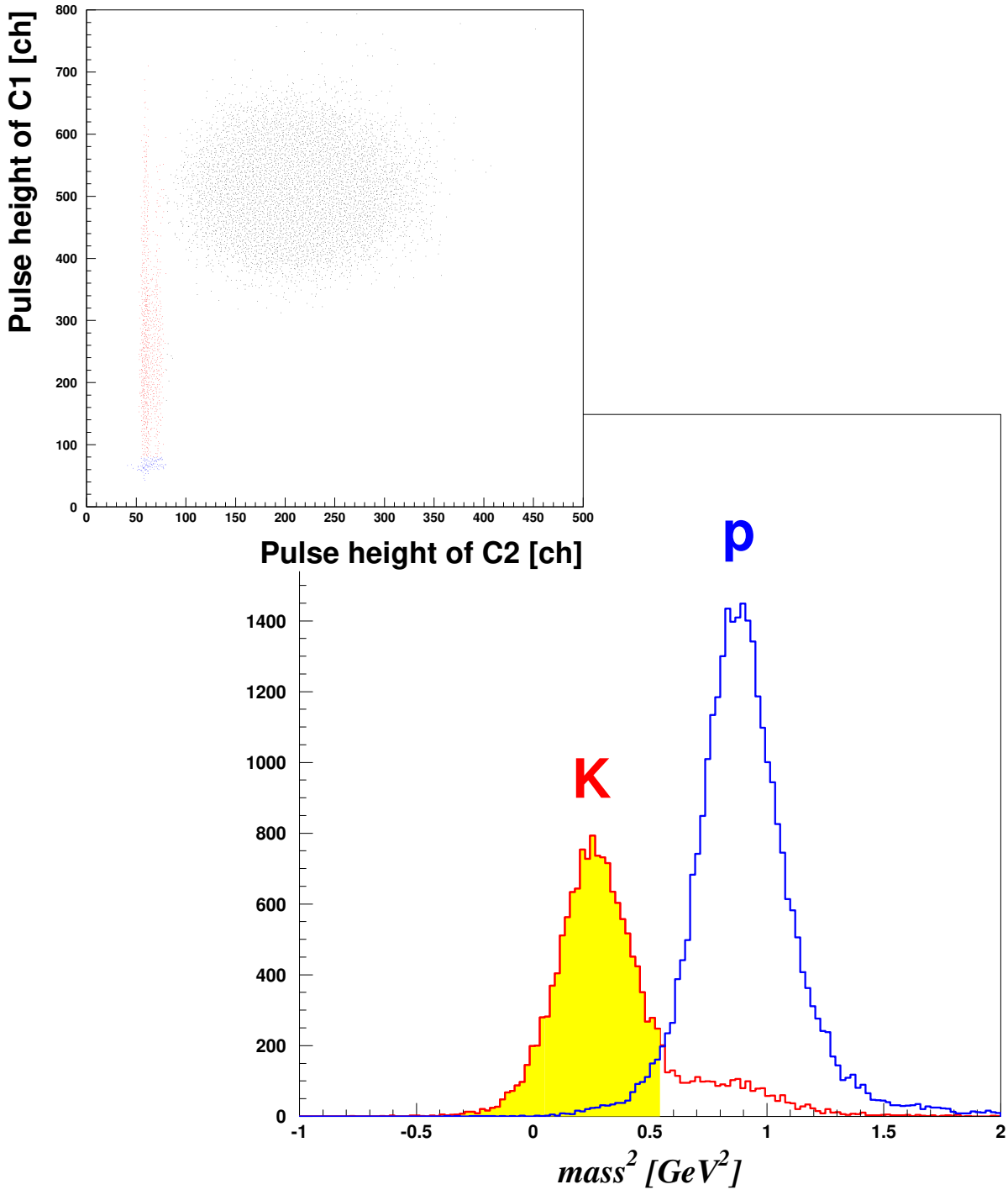
PID

- Selection between K and p