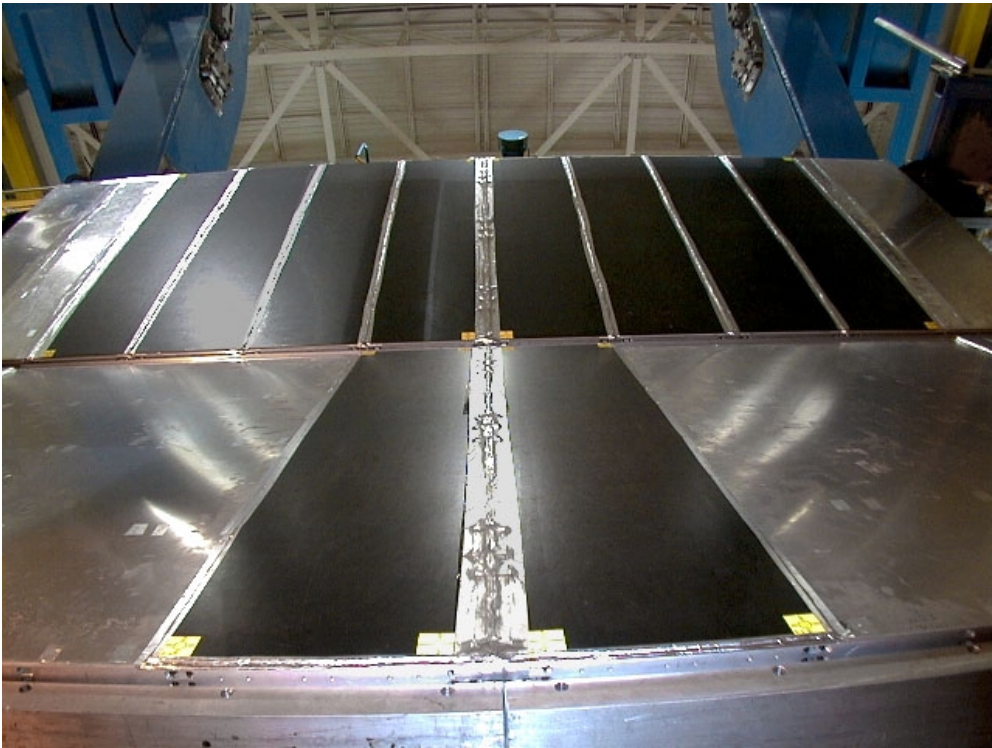


Time-of-Flight Software (Online/Offline)

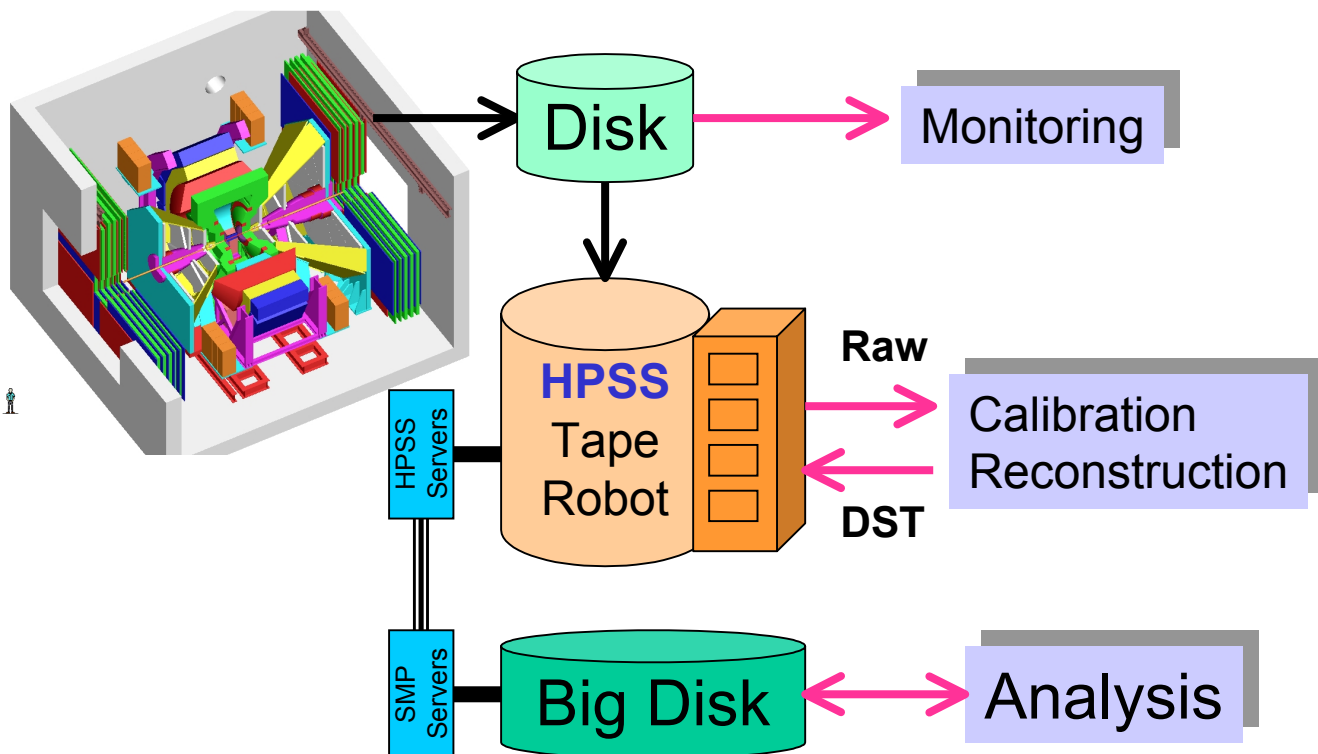


Akio Kiyomichi

Univ. of Tsukuba

Nov. 18, 1999

Online/Offline Process



- **Online**

- Monitoring

- **Offline**

- Calibration
- Reconstruction
- Physics Analysis

- Standard language for PHENIX is **C++**

Data Format

- Raw Data (DCM format)
 - **PRDF**: **P**HENIX **R**aw **D**ata **F**ormat

- TOF-PRDF

	Bits 31-29	28-20	19-16	15-0	
index					
0	0	0	15		Flag Word
1	0	0	6		Module # DCM module?
2	0	0	6		Event #
3	0	0	6		Beam CLK #
4	0	0	6		Detector ID = 0x0700
.....					
m	0	0	6		FEM Event # <--- at each FEM
m+1	0	0	6		FEM Address
m+2	0	0	6		AMU Cell Time
m+3	0	0	6		AMU Cell Pre
m+4	0	0	6		AMU Cell Post
.....					
m+n*3	0	n	12		ch N time <---- for each ch
m+n*3+1	0	n	10		ch N pre (skipped if zero
suppressed)					
m+n*3+2	0	n	9		ch N post
.....					
last-1	0	7	7		Parity Word
last	0	7	7		Last Word
.....					
Word length (no zero suppression)					
= 5 + 5*16 + 3*16*16 + 2					
= 855					

Detail information are in

http://www.phenix.bnl.gov/phenix/project_info/electronics/dcm/DCM_formats/PHENIX_Formats/tof_format_pub.htm

Data Format (cont.)

TOF Basic Tables for each slat

```
/* Raw data structure [dTofRaw.idl] */
```

```
struct dTofRaw {
    short id;           /* Reference key */
    short slatid;       /* Slat ID(0-1055)[refer to dTofGeo]*/
    short sector;       /* Sector (0-1) */
    short side;         /* South=0,North=1*/
    short panel;        /* Panel (0-3) */
    short slat;         /* Slat (0-95) */

    short cell[2];      /* AMU cell ID (0-63)
                        [0] = Lower PMT, [1] = Upper PMT */
    short qvc[2];        /* QVC value in channel (0-4095) */
    short tvc[2];        /* TVC value in channel (0-4095) */
};
```

```
/* End-product data structure [dTofReconstructed.idl] */
```

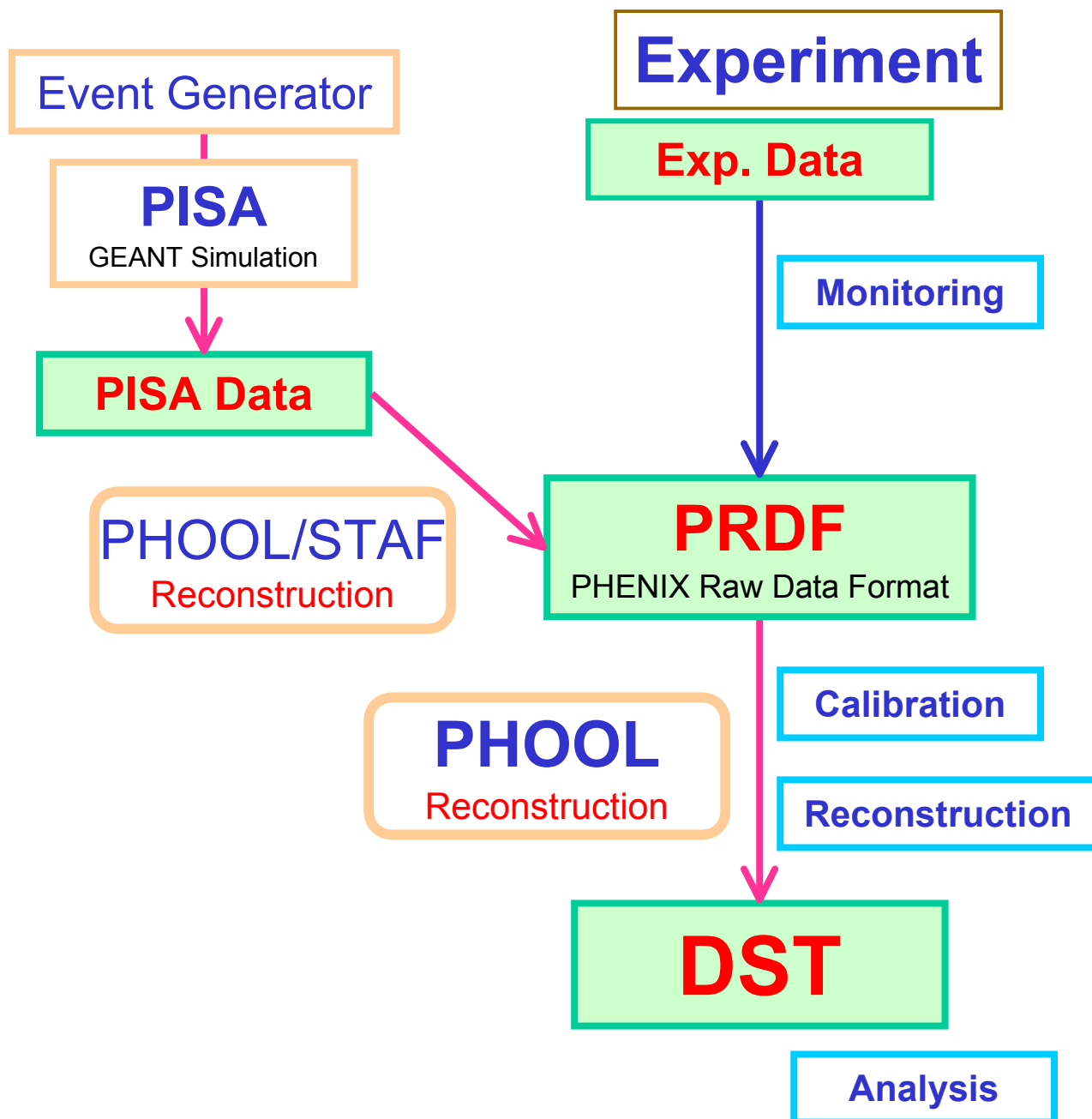
```
struct dTofReconstructed {
    short id;           /* Reference key */
    short slatid;       /* Slat ID(0-1056)[refer to dTofGeo]*/
    short sector;       /* Sector (0-1) */
    short side;         /* South=0,North=1*/
    short panel;        /* Panel (0-3) */
    short slat;         /* Slat (0-95) */

    float tof;          /* Time-of-flight */
    float eloss;        /* Energy loss */
    float xtof[3];       /* TOF hit position */
    float xtrk[3];      /* Projected track position */
};
```

Event Data I/O

- Simulation (PISA)
 - ZEBRA output
 - ROOT output (under development)
 - Create pseudo Raw data
- Monitoring, Calibration
 - read PRDF
 - write constants to Objectivity database
- Reconstruction
 - read PRDF
 - write DST
- Analysis
 - read DST
 - write histogram

Data Flow



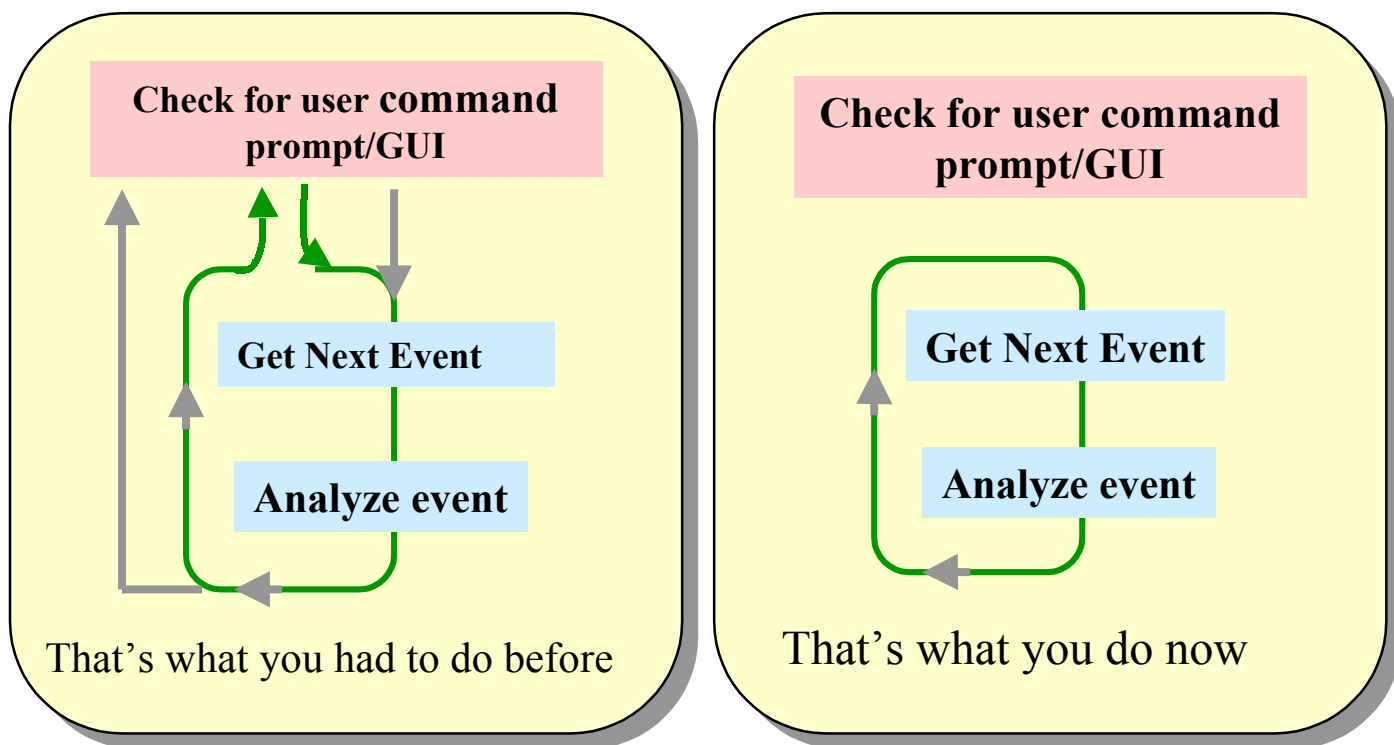
Online Software

- read from PRDF
- Platform : ROOT(monitoring), EPICS(Slow Control)
- Monitoring
 - ROOT, multi-thread ROOT
 - Pulse height (QVC gain)
 - TOF peak
 - EPICS
 - HV value
 - Temperature from ADAM
- read/write Objectivity Database
 - Geometry
 - Calibration
 - HV/Temperature

Online Tool

Multi-threaded ROOT

- Multi-thread ROOT is developed by M.Purschke. It's working.
- It will be integrated official ROOT package.



M.Purschke's Talk @computing meeting Oct.99

<http://www.phenix.bnl.gov/WWW/publish/purschke/talks/compmtg06-oct-99>

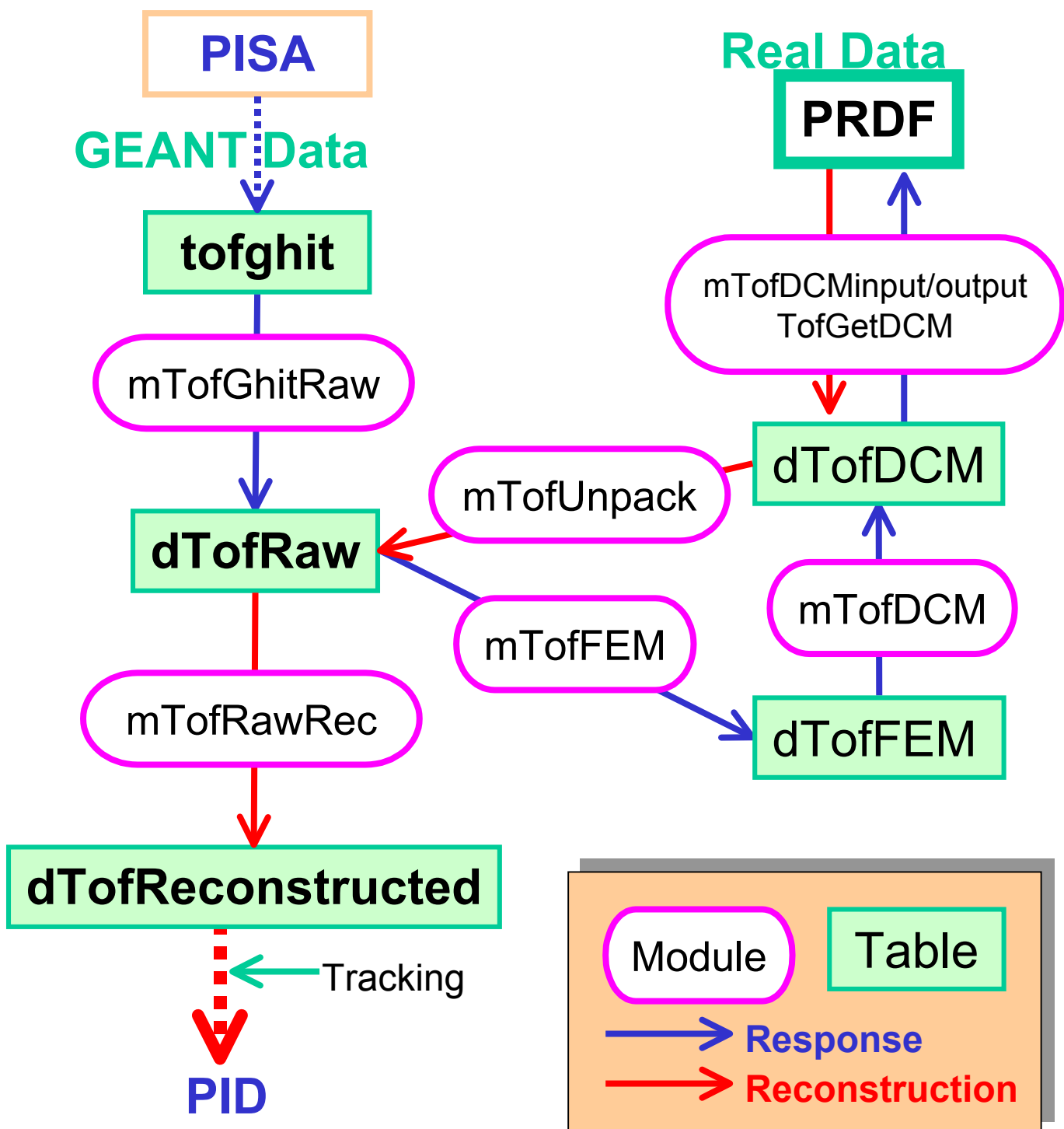
M.Kaneta's document

http://www.phenix-j.rhic.bnl.gov/tof/online/multi-threaded_root/

Offline Software

- Simulation
 - PISA: **P**HENIX **I**ntegrated **S**imulation **A**pplication
 - GEANT3 based simulation package
- Calibration
 - read PRDF
 - reach Calibration Parameters
- Reconstruction
 - convert from PRDF to DST
 - using Calibration Parameters
- Physics Analysis
 - PID, spectrum, etc,etc
- PHOOL: **P**HENIX **O**bject **O**riented **L**ibrary
 - Offline framework (I/O, Analysis)
- STAF: Old offline framework

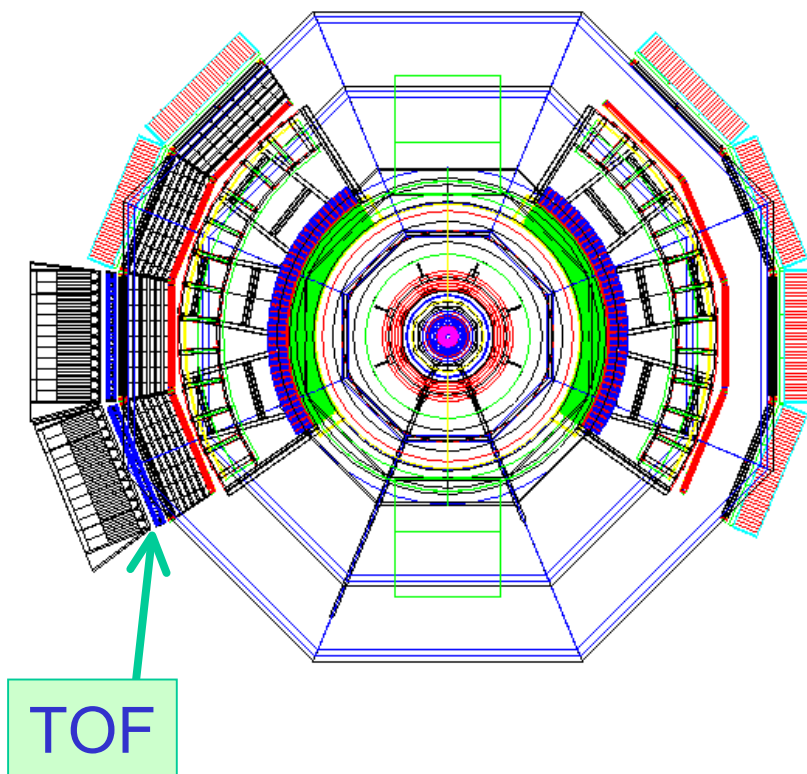
Offline Data Flow (w/Simulation)



PISA

PHENIX Integrated Simulation Application

- GEANT3 Based Simulation Package
- All of PHENIX detectors, materials
- ZEBRA output
- ROOT-in-PISA project is on going
 - ROOT formatted PISAoutput



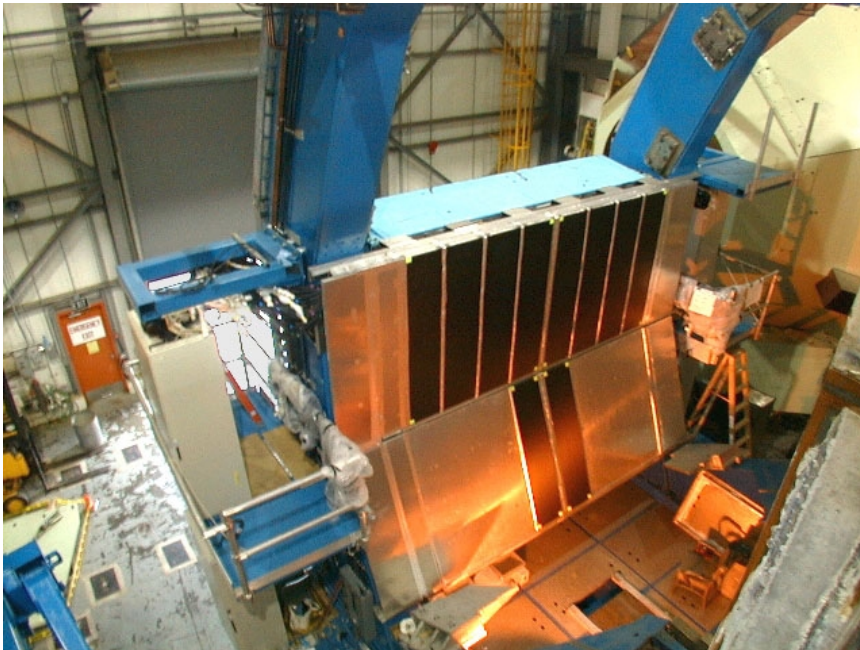
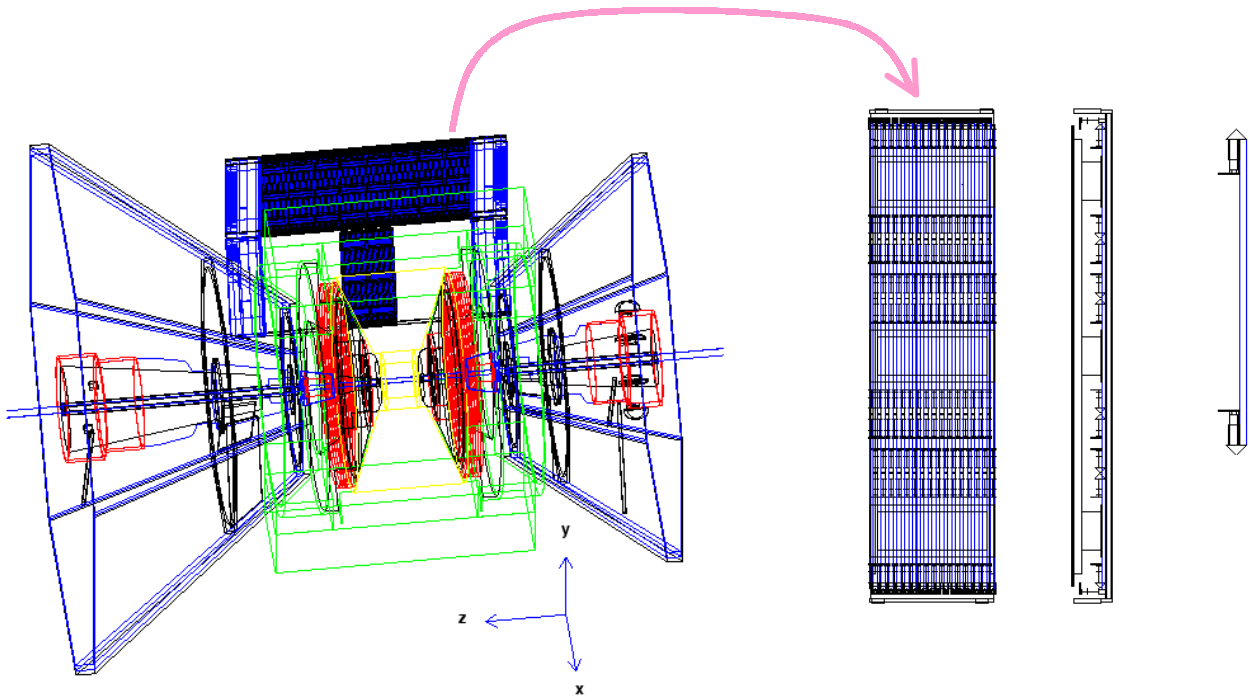
PHOOL

PHENIX Object Oriented Library

- ROOT based Class library
- A Framework for data-handling and I/O
- Flexible tree-structure in memory
- It will integrate with online system



TOF Geometry in PISA

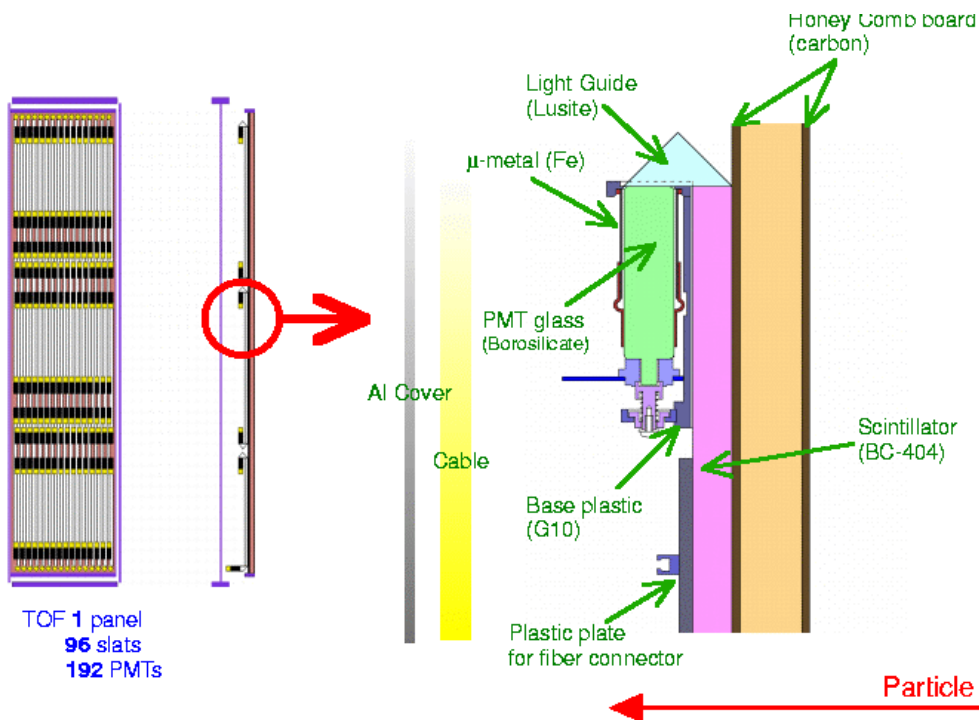


TOF 10 panels on East Arm



1 panel

TOF materials



- Sensitive volume
 - Scintillator (BC404)
- Other Materials
 - Honeycomb board
 - Cable
 - Plastic plate
 - PMT (glass, mu-metal)
 - Al frame, cover

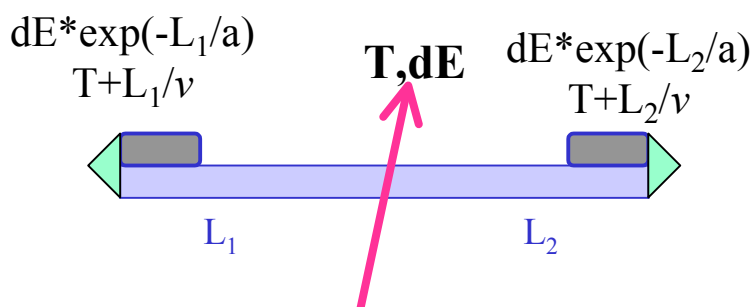
TOF Response in PISA

- Response in PISA

- Energy Loss (step by step [GUSTEP])
- Flight Times (TOF)

- Digitization (PHOOL/STAF)

- It make the digitized data for each slat.
- One data in scintillator slat separate two PMT.
- PMT gain [QVC] is converted from Energy loss
- TVC with timing resolution and slewing effect converted from flight times.



TOF Response on PHOOL

GEANT → PRDF

GEANT Data

tofghit

mTofGhitRaw

dTofRaw

mTofFEM

dTofFEM

mTofDCM

dTofDCM

mTofDCMoutput

PRDF

- Create pseudo raw data from GEANT data
- Include timing resolution, slewing effect and absorption in scintillator
- mTofGhitRaw
 - Convert GEANT/PISA hits into digitized raw data
 - (TOF, Energy loss) → (TVC,QVC)

Calibration Parameter

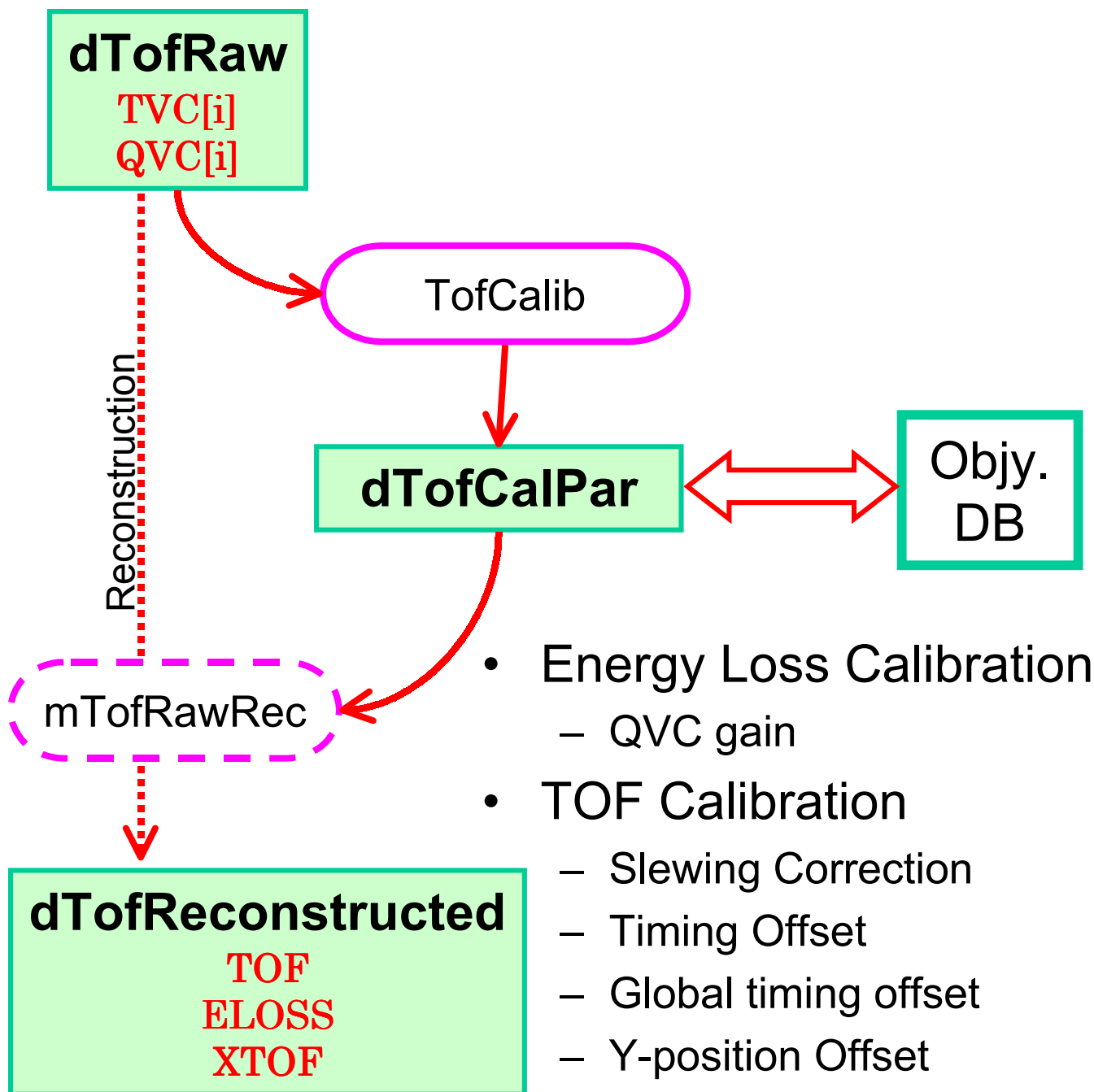
• Measurement

- $\text{TOF} = \{\text{TVC}[0] * \text{Ct}[0] + \text{TVC}[1] * \text{Ct}[1] - (s[0] + s[1])\} / 2$
 $- \text{T0}[\text{BBC}] - \text{T0} - \text{T0}[\text{global}] - \text{T0}[\text{TVC}]$
- $Y = v/2 * (\text{TVC}[0] * \text{Ct}[0] - \text{TVC}[1] * \text{Ct}[1]) + Y0$
- $\text{ELOSS} = \text{Cq} * \text{sqrt}(\text{QVC}[0] * \text{QVC}[1])$

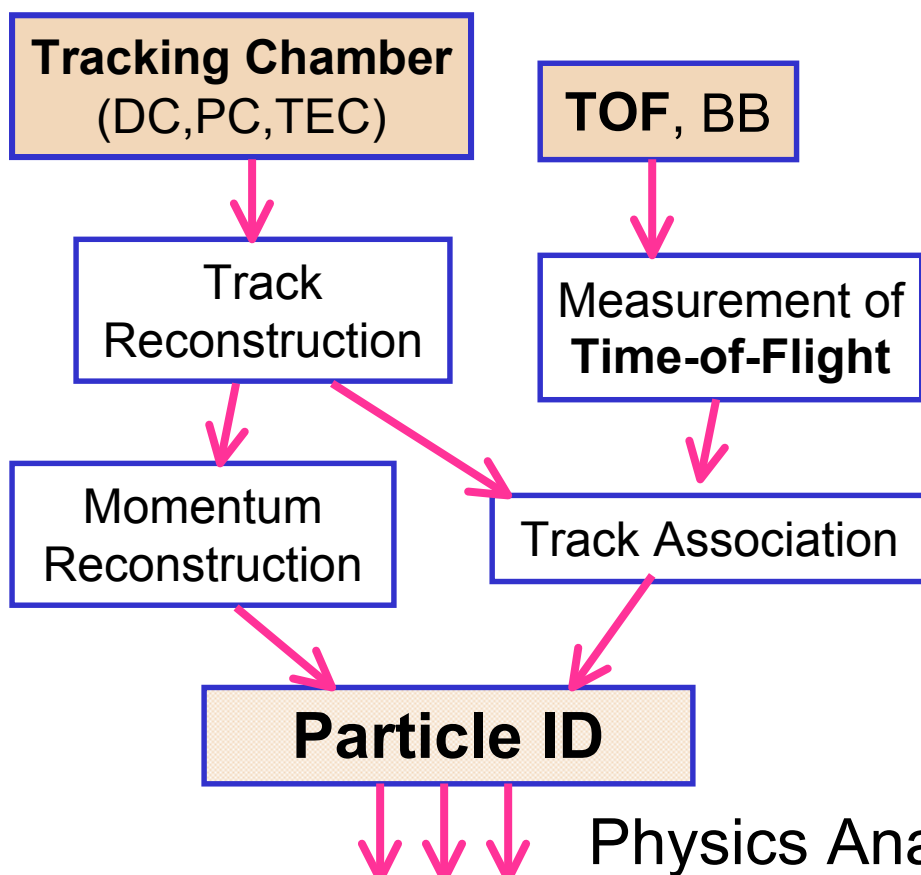
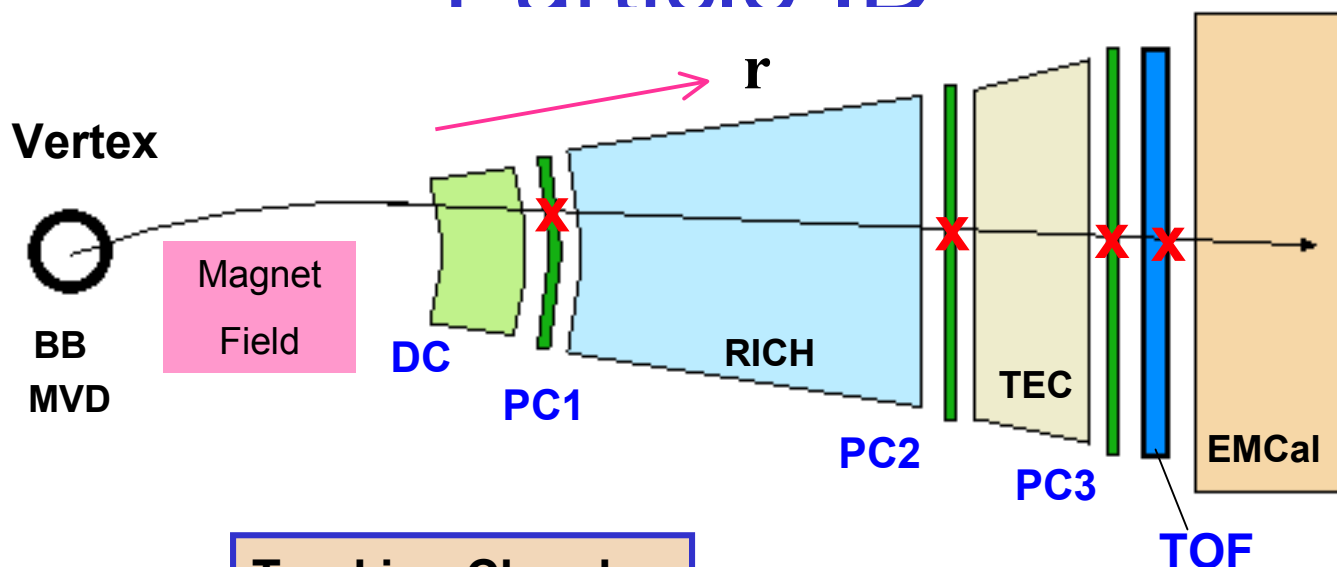
• Parameter

		No.of Parameter
–		
– T0	Time offset of each slat	No.of slats
– T0[global]	Time offset of a run	1
– T0[TVC]	Time offset of each TVC	
– Y0	Y-position offset	No.of slats
– Cq	QVC gain conversion [eV/ch]	No.of slats
– Ct[i]	TVC gain conversion [ps/ch]	No.of PMT
– s[i]	Slewing correction function	No.of PMT
–	$s[i] = a[i] + b[i] / \text{sqrt}(\text{QVC}[i])$	
– v	light velocity in the scintillator	No.of slats

Calibration Chain



Hadron Measurement Particle ID



TOF Reconstruction

PRDF → DST

Real Data

PRDF

- Reconstruct Energy loss, TOF and position from raw data

mTofDCMinput
TofGetDCM

dTofDCM

- mTofRawRec
 - Convert raw data to DST data
 - (TVC,QVC) → (TOF, Energy loss)

mTofUnpack

dTofRaw

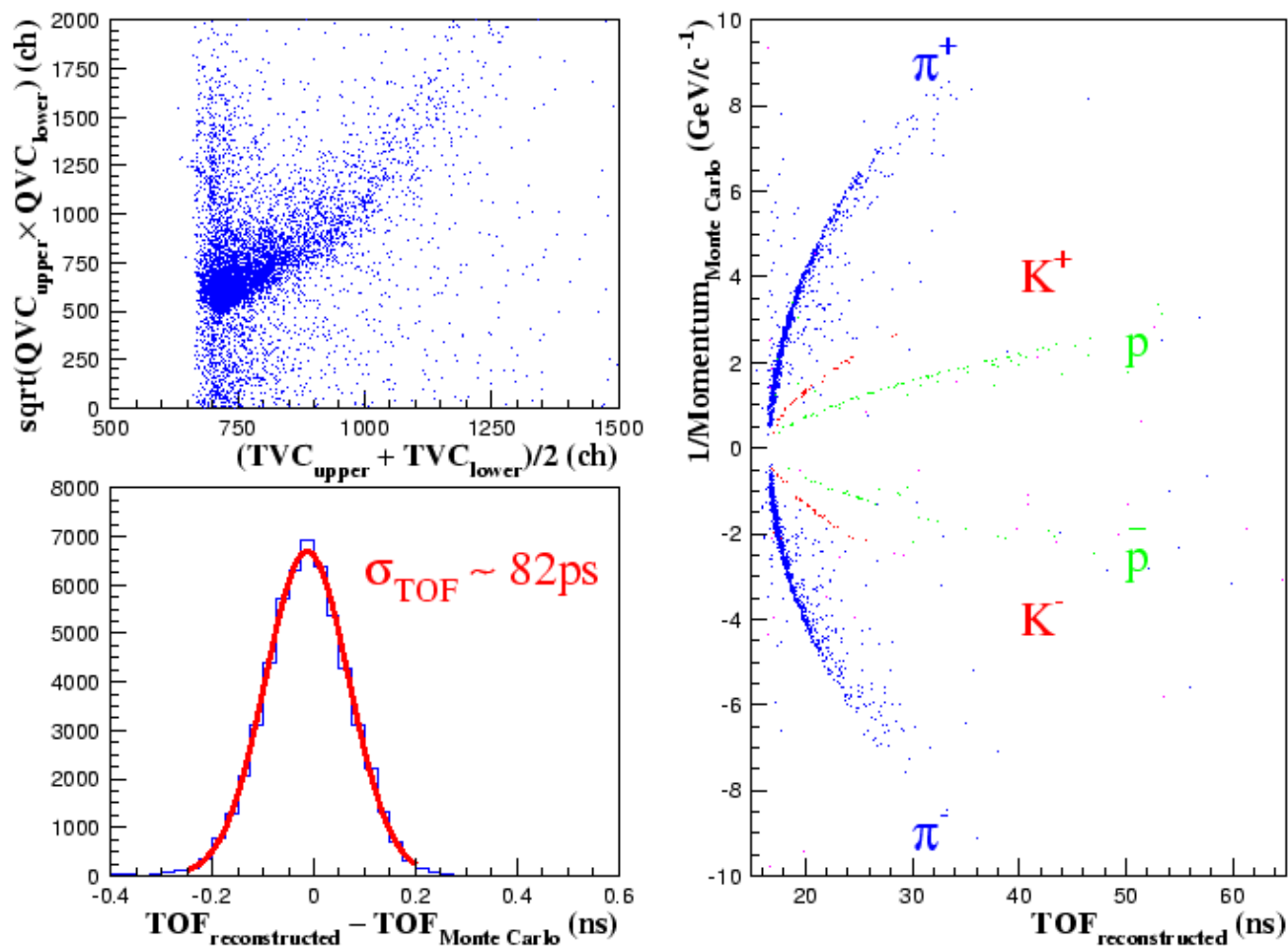
dTofCalPar

mTofRawRec

dTofReconstructed

TOF Performance Plot

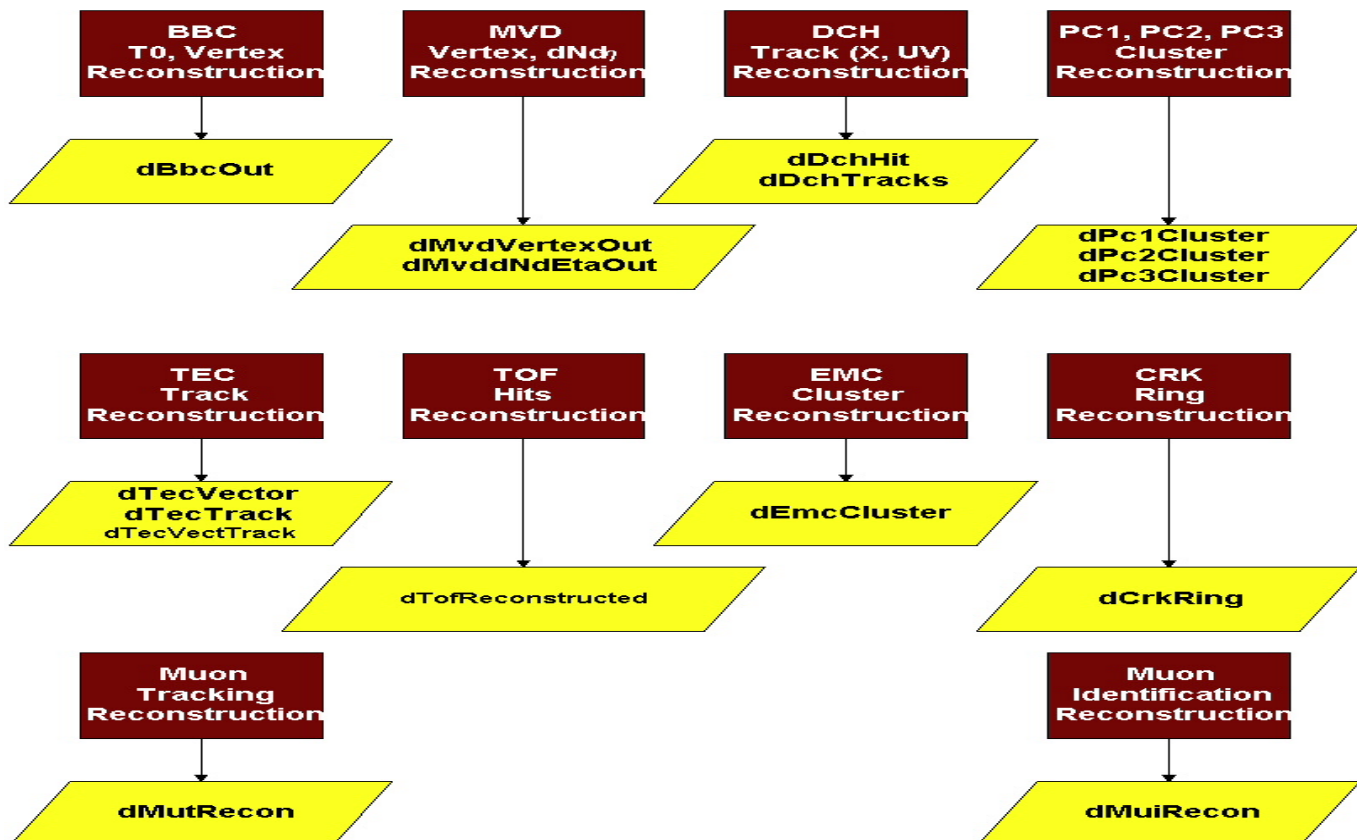
performance of TOF in 2.5K min-bias Au+Au event



- Evaluation the Reconstructed TOF data and Perfect MC data.

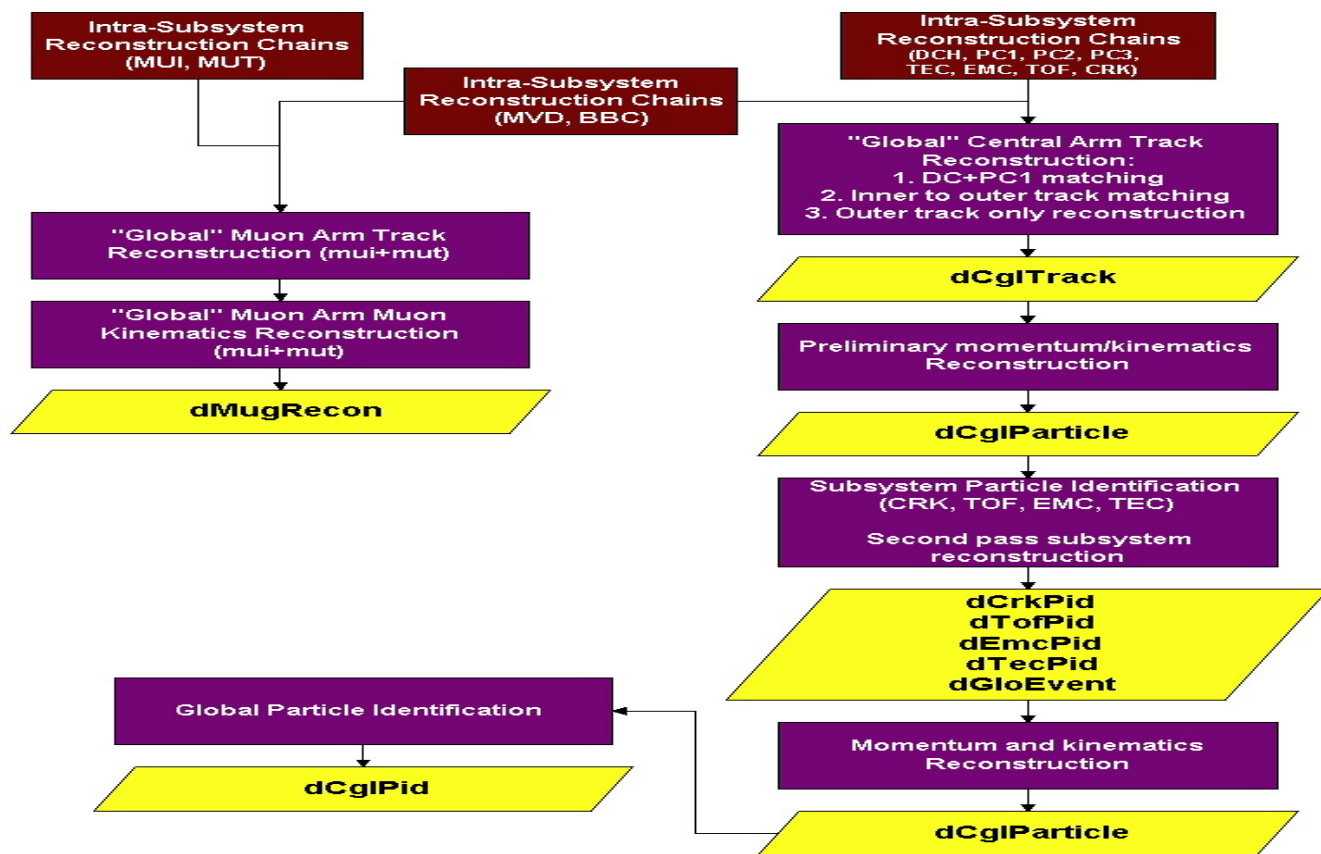
Subsystem Reconstruction

all detectors



Global Tracking

Inter-Subsystem Reconstruction Analysis Flow

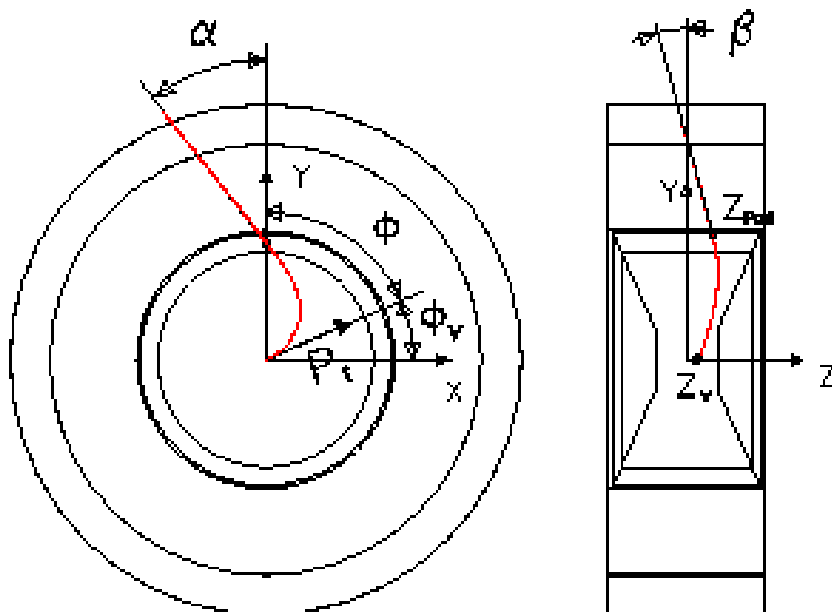


- maintained by Jeffery T. Mitchell(BNL)

<http://www.phenix.bnl.gov/WWW/software/luxor/>

Momentum Reconstruction

Angle α between track and straight line from $R=0$ through track intercept at fixed radius.



β, Z_{pad} determined from track projection in plane containing a line.

$$1/p_T, \theta, z_v \longleftrightarrow \alpha, \beta, Z_{\text{pad}}$$

Conclusion & Status

- The official language for PHENIX is C++
- The standard framework for PHENIX is ROOT

• Online

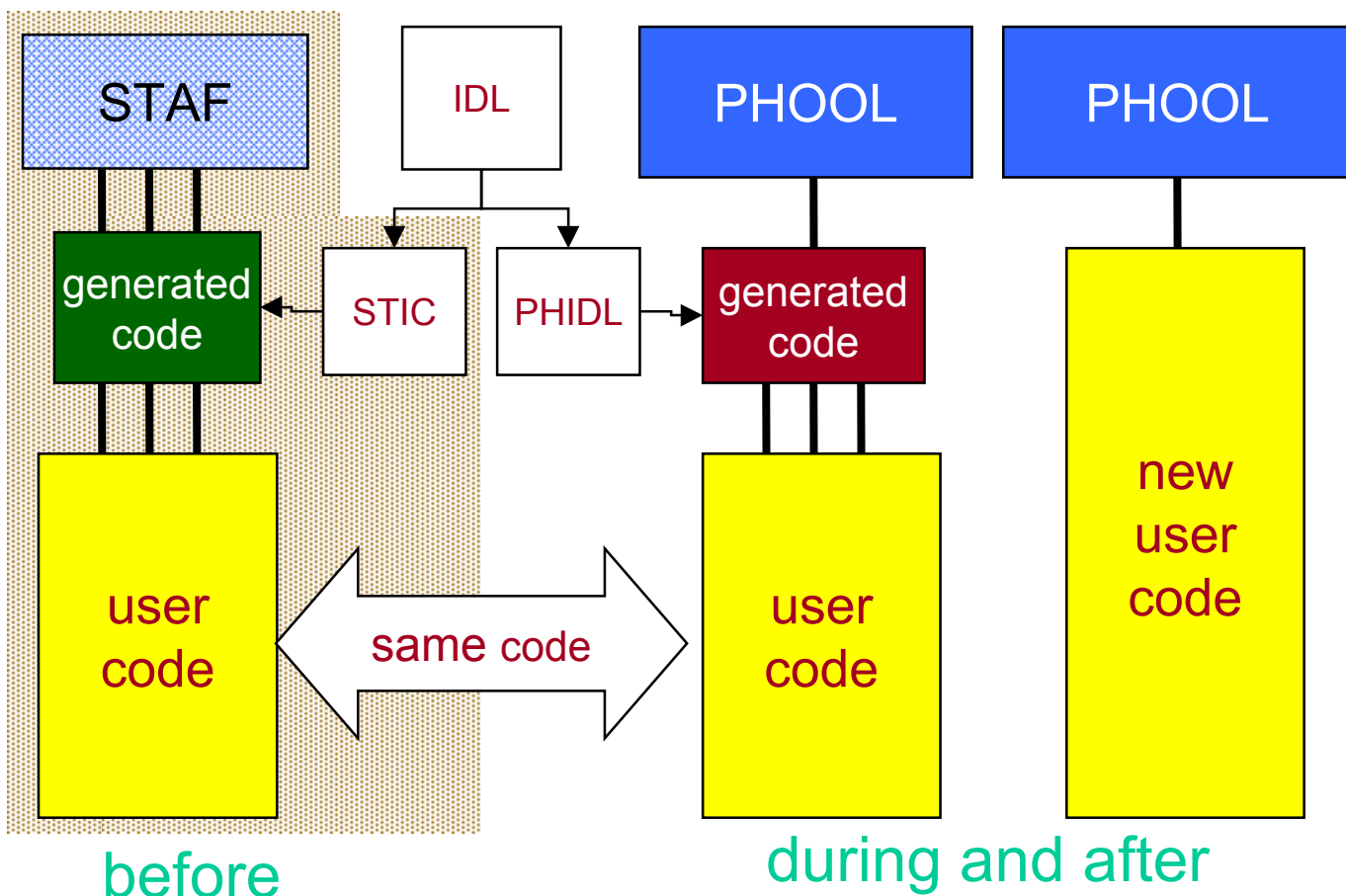
- Y.S. and E.K. started developing TOF online monitoring.
- M.K. followed multi-thread ROOT and made a document.
- K.K. developed HV control system using EPICS.

• Offline

- A.K. maintain all of offline code.
- A.K. started developing calibration code.

STAF/PHOOL

before, during and after



- Most user codes were developed on STAF.
- STAF codes are working on PHOOL by Wrapper.
- New user code should be developed on PHOOL.