

# Highly Pixelated Transparent Devices for Future Vertex Detectors

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(on behalf of the MIMOSA, PLUME, Hadron Physics 2 & AIDA collaborations)

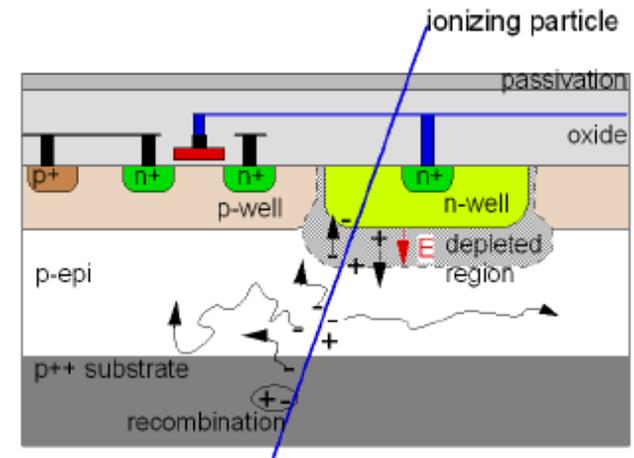
▷ more information on IPHC Web site: <http://www.iphc.cnrs.fr/-CMOS-ILC-.html>

## CONTENTS

- CMOS pixel sensors developed by IPHC (& IRFU) : Main Features
- Achieved performances & and Applications
- Plans for the coming 3-4 years
- Summary

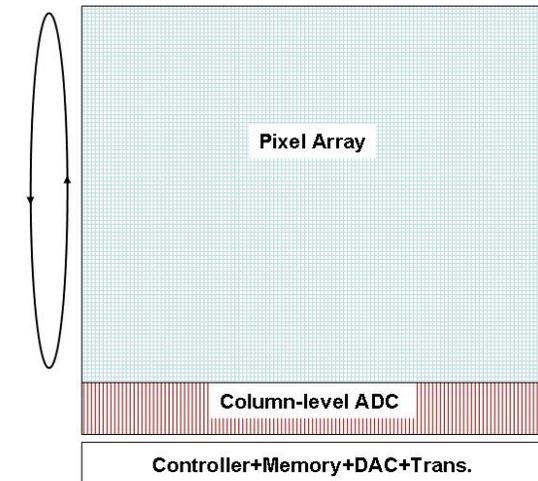
- **Prominent features of CMOS pixel sensors:**

- ✧ high granularity  $\Rightarrow$  excellent (micronic) spatial resolution
- ✧ very thin (signal generated in 10-20  $\mu\text{m}$  thin epitaxial layer)
- ✧ signal processing  $\mu$ -circuits integrated on sensor substrate



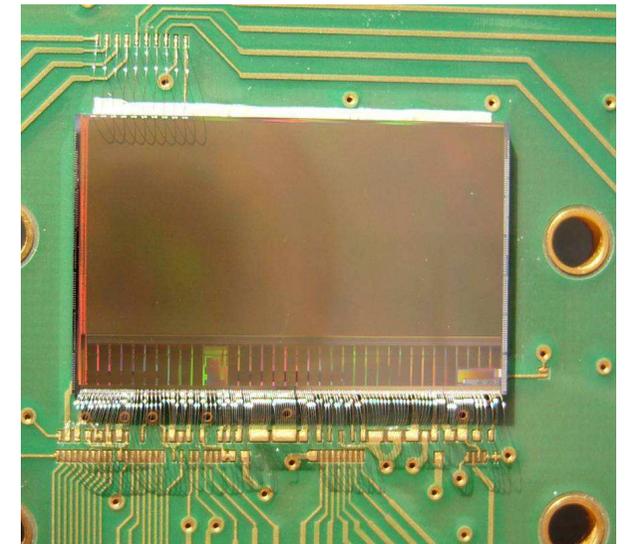
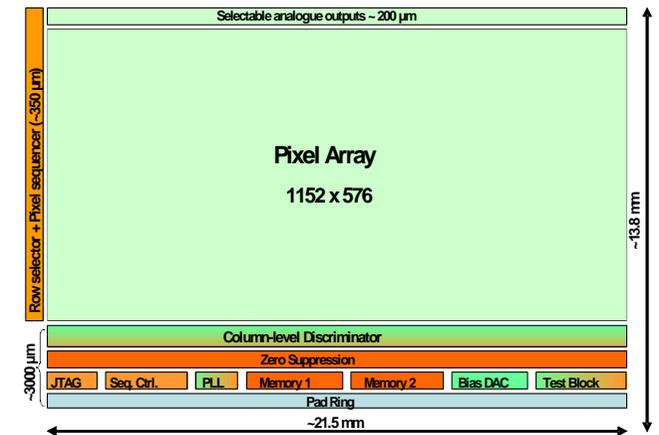
- **Sensor organisation:**

- ✧ signal sensing and analog processing in pixel array
- ✧ mixed and digital circuitry integrated in chip periphery
- ✧ read-out in rolling shutter mode  
(pixels grouped in columns read out in //)

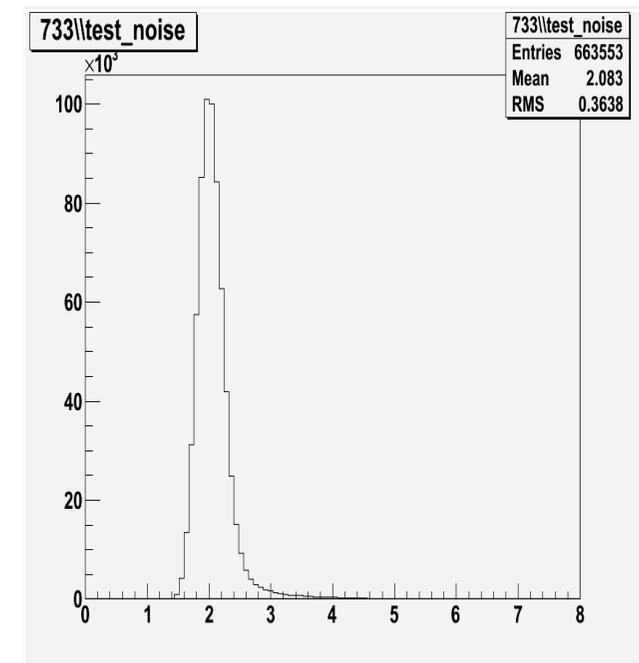
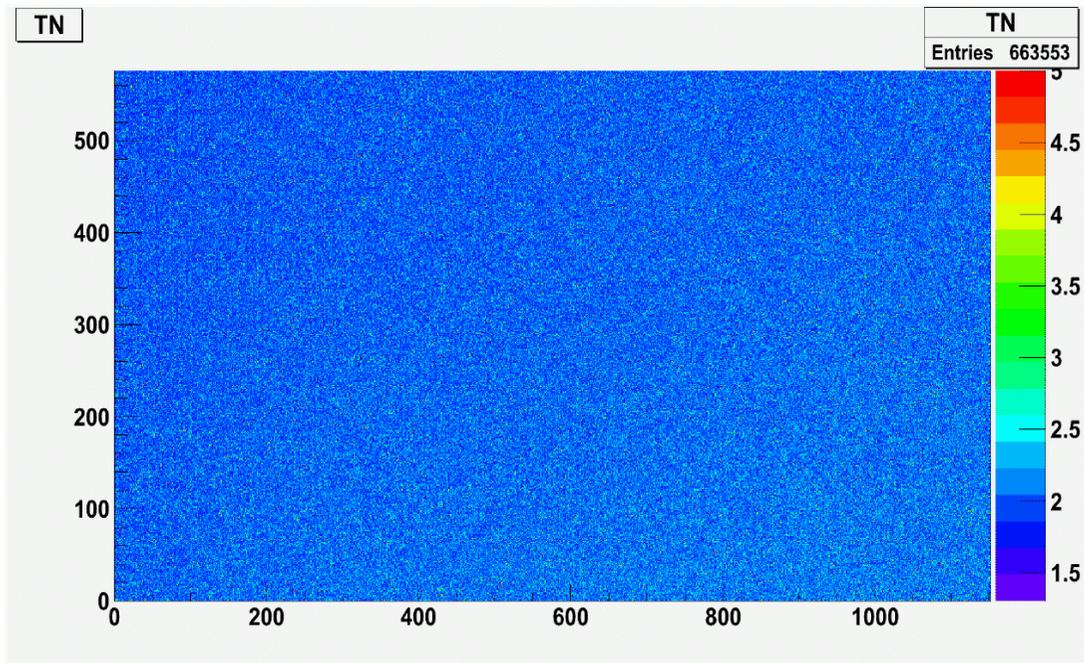


- Main characteristics of MIMOSA sensor equipping EUDET BT:

- ✧  $0.35 \mu\text{m}$  process with high-resistivity epitaxial layer (coll. with IRFU/Saclay)
- ✧ column // architecture with in-pixel amplification (CDS) and end-of-column discrimination, followed by  $\emptyset$
- ✧ active area: 1152 columns of 576 pixels ( $21.2 \times 10.6 \text{ mm}^2$ )
- ✧ pitch:  $18.4 \mu\text{m} \rightarrow \sim 0.7$  million pixels  
charge sharing  $\Rightarrow \sigma_{sp} \lesssim 4 \mu\text{m}$
- ✧  $t_{r.o.} \lesssim 100 \mu\text{s}$  ( $\sim 10^4$  frames/s)  
 $\Rightarrow$  suited to  $> 10^6$  part./ $\text{cm}^2/\text{s}$
- ✧  $\sim 250 \text{ mW}/\text{cm}^2$  power consumption (fct of  $N_{col}$ )



# MIMOSA-26 Lab Tests: Noise Performance

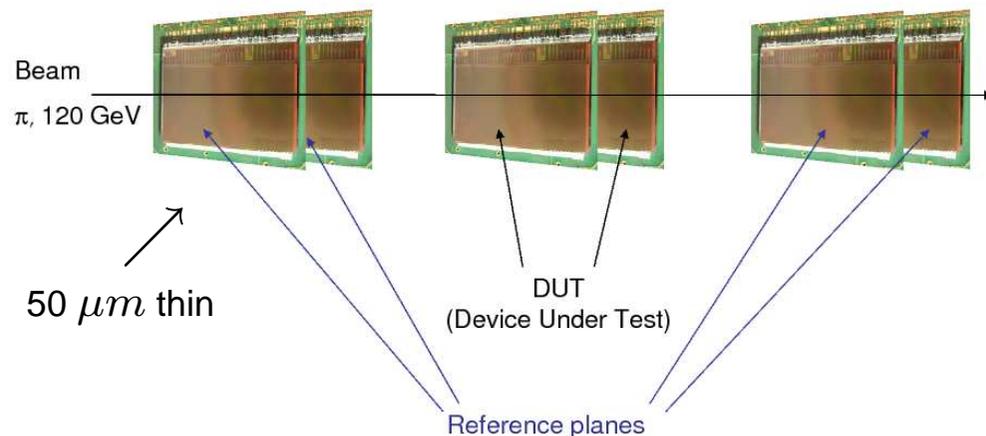


- Noise uniformity tested on  $> 60$  sensors (analogue output)
- Main conclusions:
  - \* no dead pixel over  $> 50$  arrays of 665,000 pixels !
  - \*  $N \lesssim 14 e^- \text{ENC}$
  - \* marginal noise dispersion between chips

# High-Resistivity CMOS Pixel Sensors

## ● M.i.p. detection with LOW & HIGH resistivity CMOS sensors combined in a Beam Telescope (BT)

- ✧ 4 EUDET ref. sensors & 2 sensors under test
- ✧ June 2010 at CERN-SPS ( $\sim 120$  GeV pions)
- ✧ sensor variants : standard epitaxy ( $14 \mu m$  thick)  
& high-resistivity epitaxy ( $10$  &  $15 \mu m$  thick)



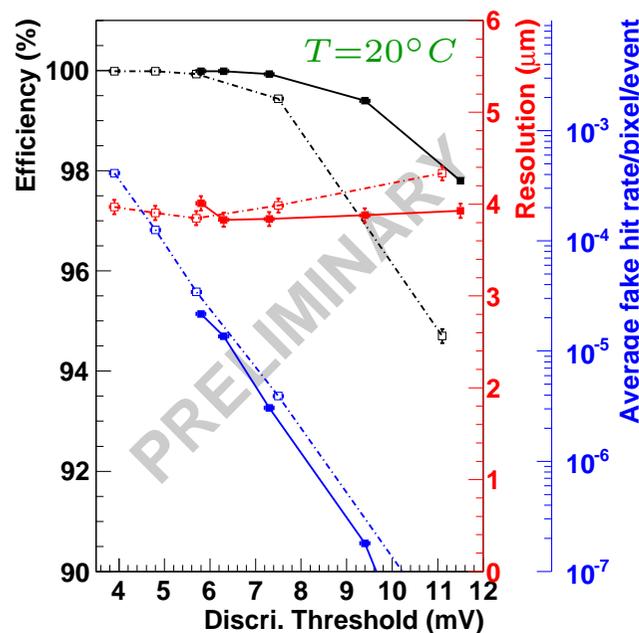
## ● Main Results:

- ✧ det. eff.  $\sim 100\%$  (SNR  $\sim 40$ ) for very low fake rate:  
▷ plateau until fake rate of few  $10^{-6}$
- ✧ single point resolution  $\lesssim 4 \mu m$
- ✧ det. eff. still  $\sim 100\%$  after exposure  
to fluence of  $1 \cdot 10^{13} n_{eq}/cm^2$

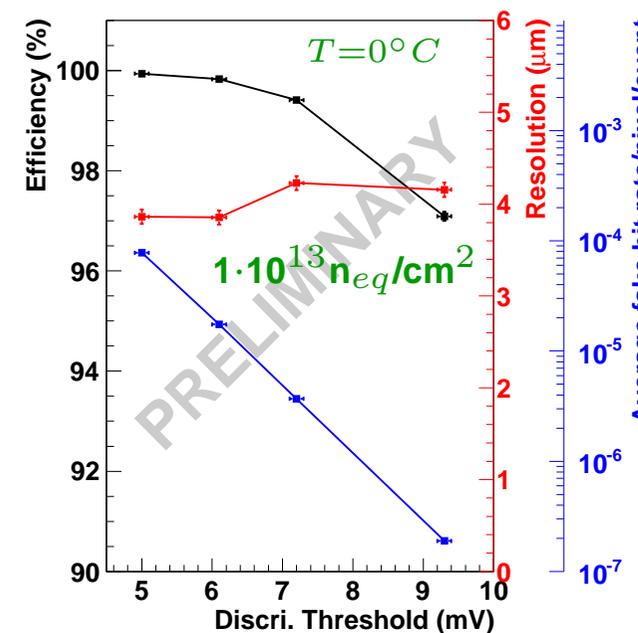
⇒ **Excellent detection performances with high-resistivity epitaxial layer** despite moderate resistivity ( $400 \Omega \cdot cm$ ) and poor depletion voltage ( $< 1$  V)

⇒ **Tolerance to  $\gtrsim O(10^{14}) n_{eq}/cm^2$  seems within reach (study under way)**

Mi26 HR-15 and HR-10 Efficiency, Fake rate and Resolution

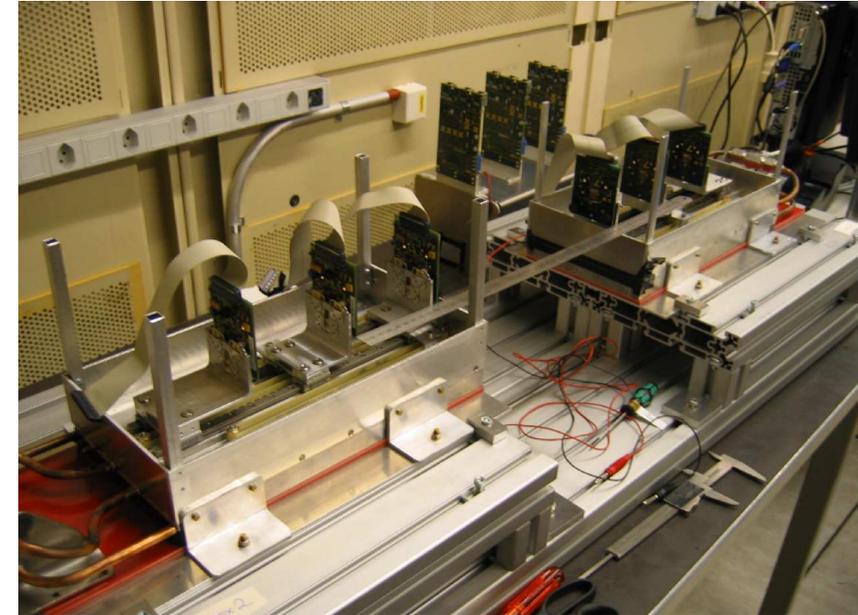


Mi26 HR-15 Efficiency, Fake rate and Resolution for a chip irradiated with a  $1 \cdot 10^{13} n_{eq}$  dose at  $T_{op} \sim 0^\circ C$



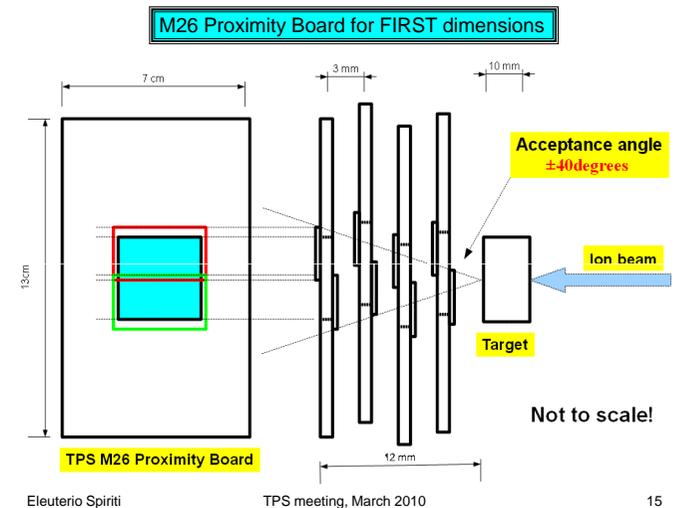
# Direct Applications of MIMOSA-26

- **Beam telescope of the FP6 project EUDET**
  - ✧ 2 arms of 3 planes (plus 1-2 high resolution planes)
  - ✧ M-26 thinned to  $50 \mu m$
  - ✧  $\sigma_{extrapol.} \sim 1-2 \mu m$  EVEN with  $e^-$  (3 GeV, DESY)
  - ✧ frame read-out frequency  $O(10^4)$  Hz
  - ✧ running since '07 (demonstrator: analog outputs)  
at CERN-SPS & DESY (numerous users)

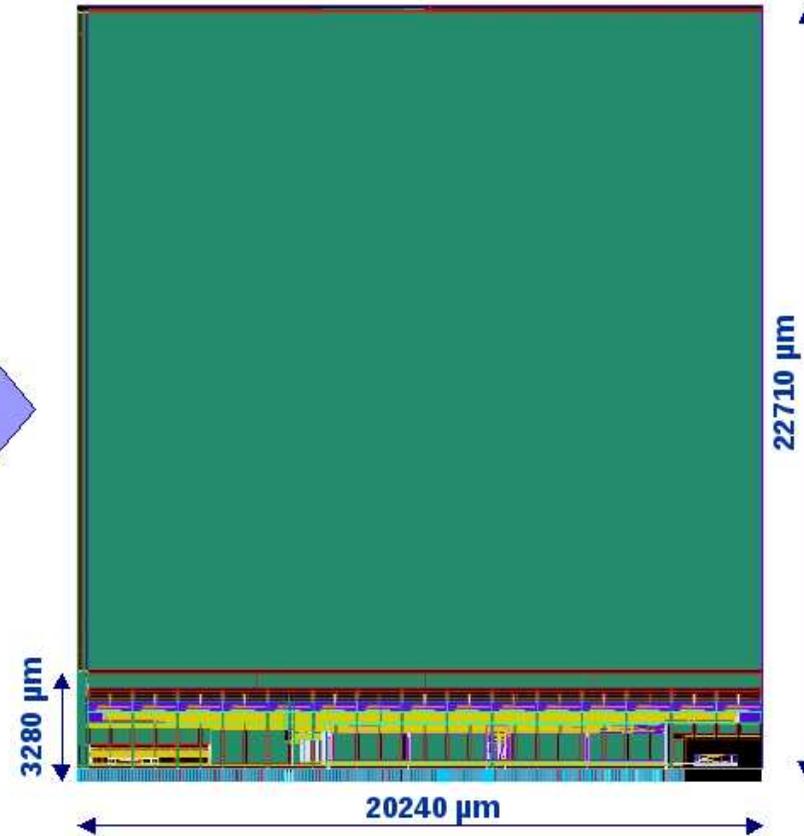
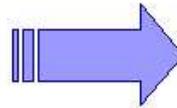
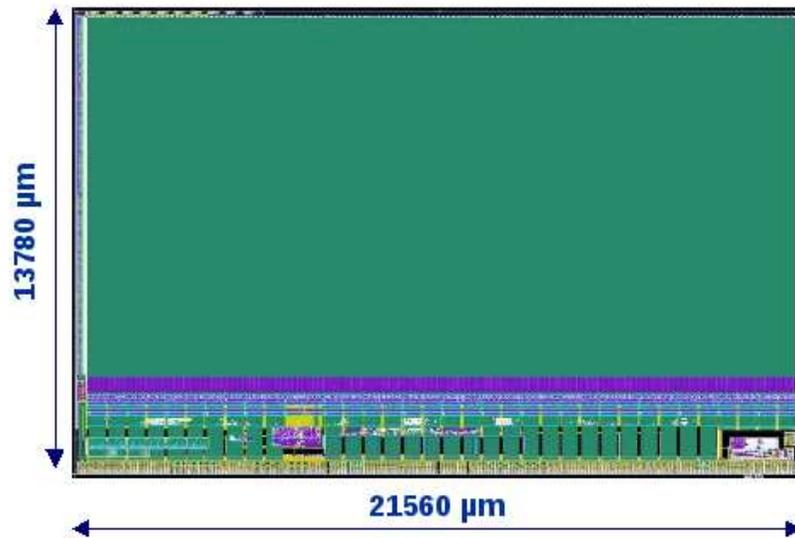


- **Spin-offs :**

- ✧ **Several BT copies :** foreseen for detector R&D
- ✧ **BT for channelling studies, mass spectroscopy, etc.**
- ✧ **CBM (FAIR) :** MVD demonstrator (2-sided layers) for CBM-MVD (HP-2 project)
- ✧ **FIRST (GSI) :** VD for hadrontherapy  $\sigma$  measurements



# From MIMOSA-26 to ULTIMATE



- Half reticle 1152 x 567 pixel matrix
- Temperature  $\sim 20$  °C
- Light power consumption constrains
- Space resolution  $\sim 4$   $\mu\text{m}$
- No constrains on radiation tolerance

- Full reticle 960 x 928 pixel matrix
  - ↳ Longer integration time  $\sim 200$   $\mu\text{s}$
- Temperature 30-35 °C
- Power consumption  $\sim 100$  mW/cm<sup>2</sup>
- Space resolution  $< 10$   $\mu\text{m}$
- 150 kRad / yr & few  $10^{12}$  Neq /cm<sup>2</sup> /yr

**→ Optimisation**

courtesy of Ch. Hu-Guo / TWEPP-2010

# Ultimate Pixel Performances

- Summary of results obtained with S7 (CS) :

- ✧ detection efficiency vs discri. threshold

- ✧ fake hit rate vs discri. threshold

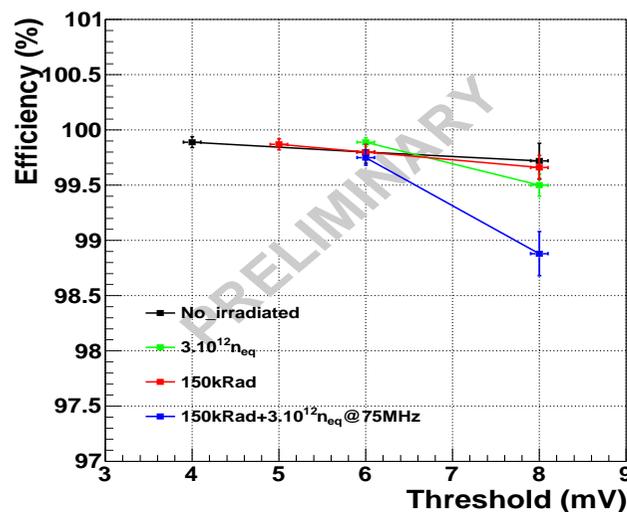
- ↪ look for viable working point

(fake  $< 10^{-4}$ )

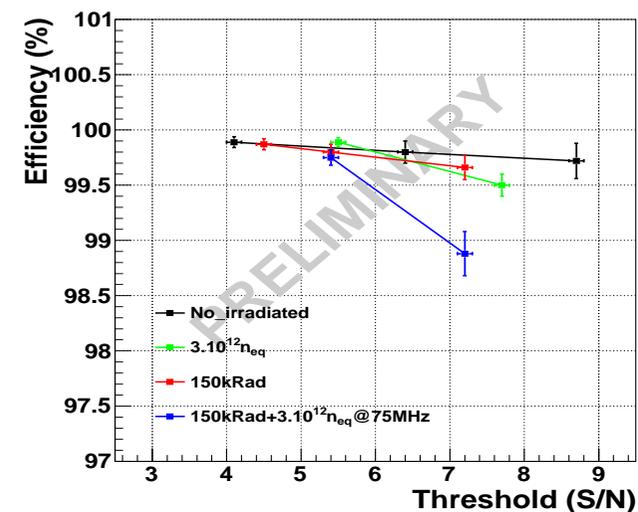
- Results for 20.7  $\mu m$  pitch pixels ▷

mV-SNR equivalence at 30°C

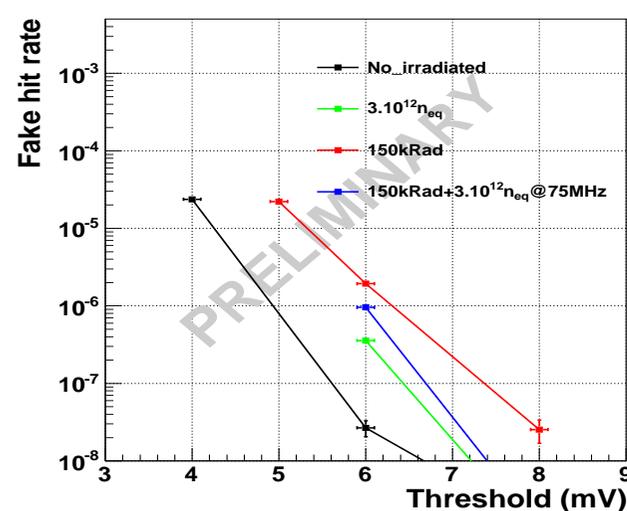
Efficiency vs Threshold



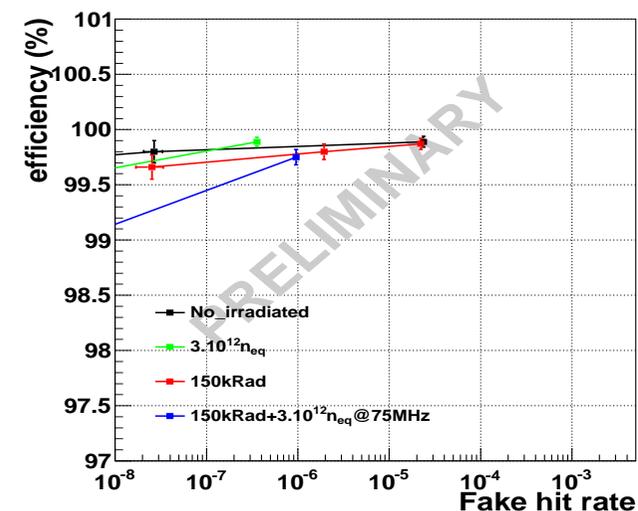
Efficiency vs Threshold



Fake hit rate (whole sensor) vs Threshold



Efficiency vs Fake hit rate

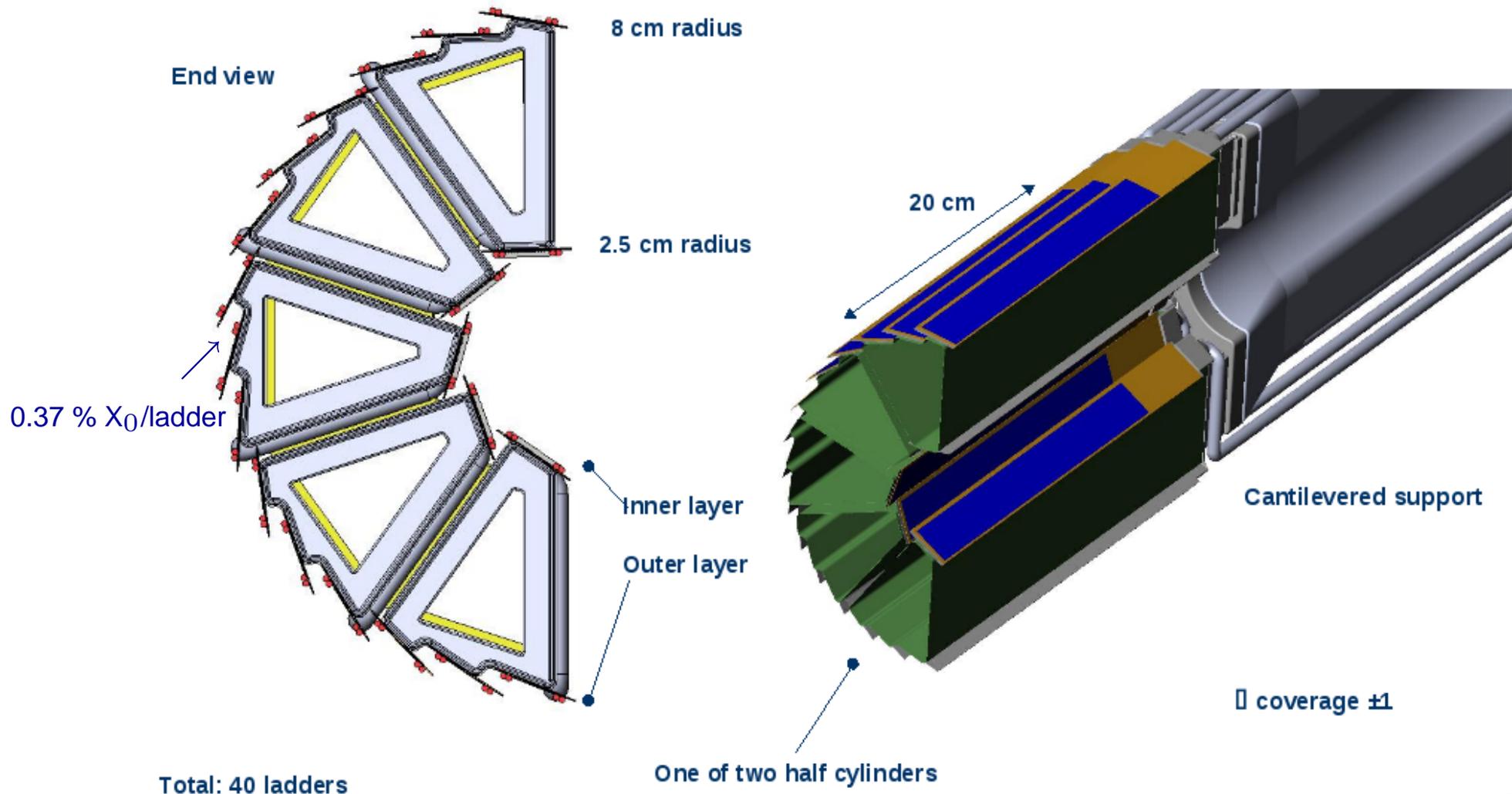


Threshold (mV) ▷	4	5	6	8
before irradi.	4.1		6.4	8.7
3.10 <sup>12</sup> n <sub>eq</sub> /cm <sup>2</sup>			5.5	7.7
150 kRad		4.5	5.4	7.2
combined (75 MHz)			5.2	6.9

⇒ No problem to find a threshold where the detection efficiency is  $> 99.5\%$  while the fake hit rate remains marginal

# Application of CMOS sensors to the STAR-PXL

The detector ladders are 50  $\mu\text{m}$  thinned silicon, on a flex kapton/aluminum cable.



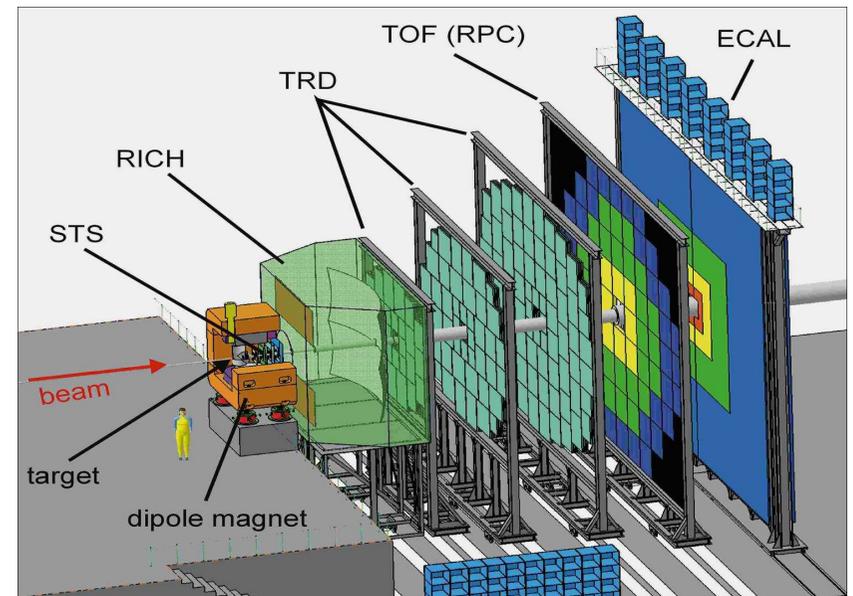
courtesy of Michal Szelezniak / Vertex-2010

▷▷▷ 1st vertex detector equipped with CMOS pixel sensors → 1st data taking in 2012/13

## Next Extensions of MIMOSA-26

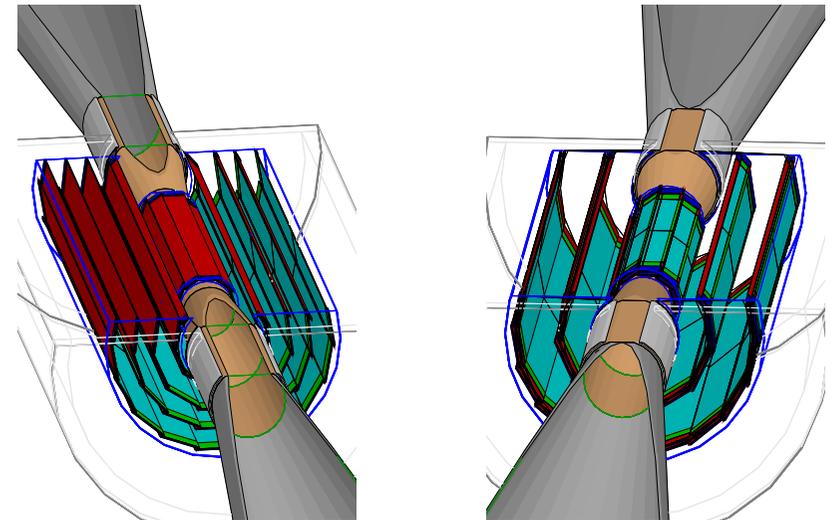
- **Vertex Detector of the CBM expt / FAIR**

- \* 2 double-sided stations operated in vacuum
- \* 0.3–0.5 %  $X_0$  per station
- \*  $\lesssim 5 \mu m$  single pt resolution
- \*  $\lesssim 10 \mu s$  r.o. time
- \* several MRad &  $> 10^{13} n_{eq}/cm^2/s$  ( $T < 0^\circ C$ )
- \* data taking  $\gtrsim 2016$  (SIS-100) ... 2020 (SIS-300)



- **ILD Vertex Detector (option) :**

- \* geometry : 3 double-sided or 5 single-sided layers
- \*  $\sim 0.2 \% X_0$  total material budget per layer
- \*  $\sigma_{sp} \lesssim 3 \mu m$
- \* r.o. time  $\lesssim 25\text{--}100 \mu s$  (500 GeV)



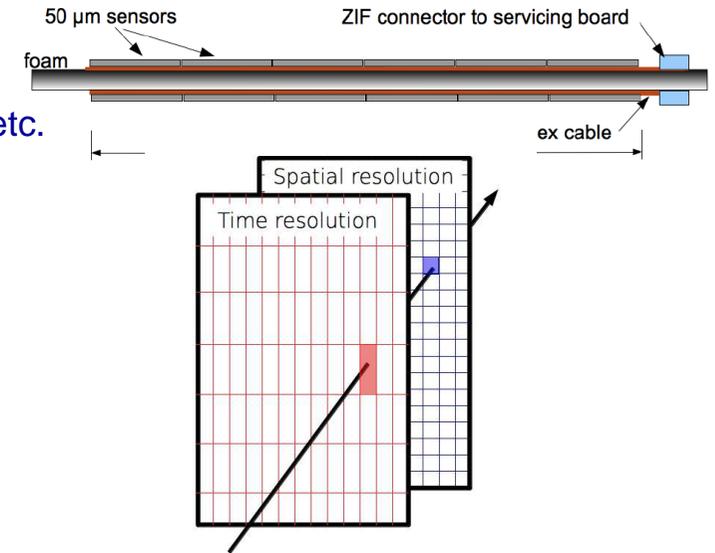
- **Other applications under consideration :**

ITS/ALICE upgrade, FOCAL/ALICE, VD/EIC, VD/CLIC, (HL-)LHC upgrades, etc.

# Sensor Integration in Ultra Light Devices

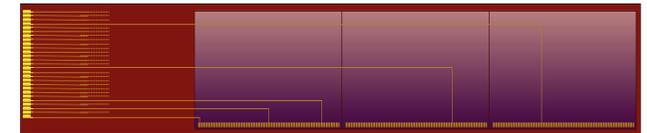
## ● Double-sided ladders with time stamping :

- ✧ manyfold bonus expected from 2-sided ladders:  
compactness, alignment, pointing accuracy (shallow angle), redundancy, etc.
- ✧ studied by PLUME coll. (Oxford, Bristol, DESY, IPHC) & AIDA (EU)  
↳ Pixelated Ladder using Ultra-light Material Embedding
- ✧ square pixels for single point resolution on beam side
- ✧ elongated pixels for 4-5 times shorter r.o. time on other side
- ✧ correlate hits generated by traversing particles
- ✧ expected total material budget  $\sim 0.2 - 0.3 \% X_0$



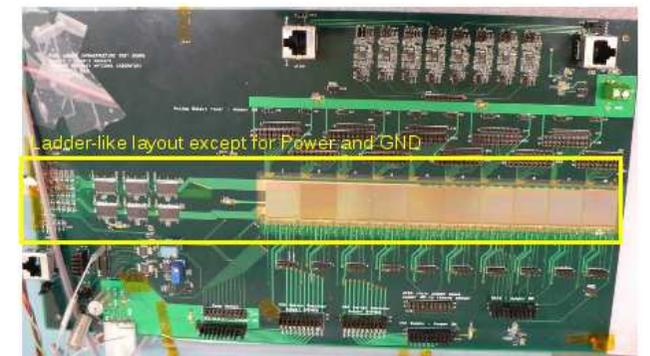
## ● Unsupported & flexible (?) ladders (Hadron Physics 2 / FP-7)

- ✧ 30  $\mu m$  thin CMOS sensors mounted on thin cable  
and embedded in thin polyimide  $\rightarrow$  suited to beam pipe ?
- ✧ expected total material budget  $\lesssim 0.15 \% X_0$



## ● STAR-PXL ladder:

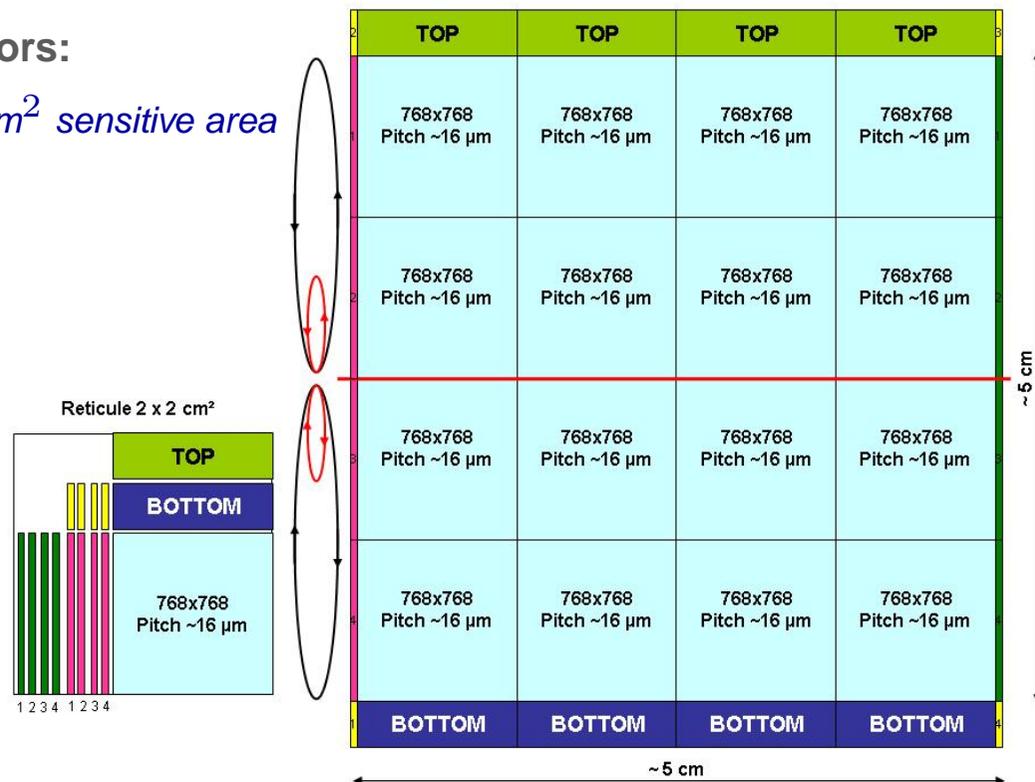
- ✧ total material budget  $\sim 0.37 \% X_0$   
 $\Rightarrow$  would be  $\sim 0.3 \% X_0$  with less stiffener (vibrations)



# Investigating Large Area Sensors

- **Prototype multireticule sensor for "large" area detectors:**

- ✳  $2304/3072 \times 2304/3072$  pixels ( $22/16 \mu\text{m}$  pitch)  $\Rightarrow 5 \times 5 \text{ cm}^2$  sensitive area
- ✳ requires combining several reticules
  - $\Rightarrow$  stitching process  $\Rightarrow$  establish proof of principle
- ✳ 2-sided read-out of 1152/1536 rows in 200-300  $\mu\text{s}$ 
  - $\Rightarrow$  Large Area Telescope for AIDA project  
(EU-FP7 approved recently)
- ✳ windowing of  $\lesssim 1 \times 5 \text{ cm}^2$  (collim. beam)
  - $\Rightarrow \lesssim 50\text{--}60 \mu\text{s}$  r.o. time
- ✳ 50-100  $\mu\text{m}$  pitch variants under consideration
  - $\Rightarrow$  trackers & FW disks (e.g. VD for EIC)

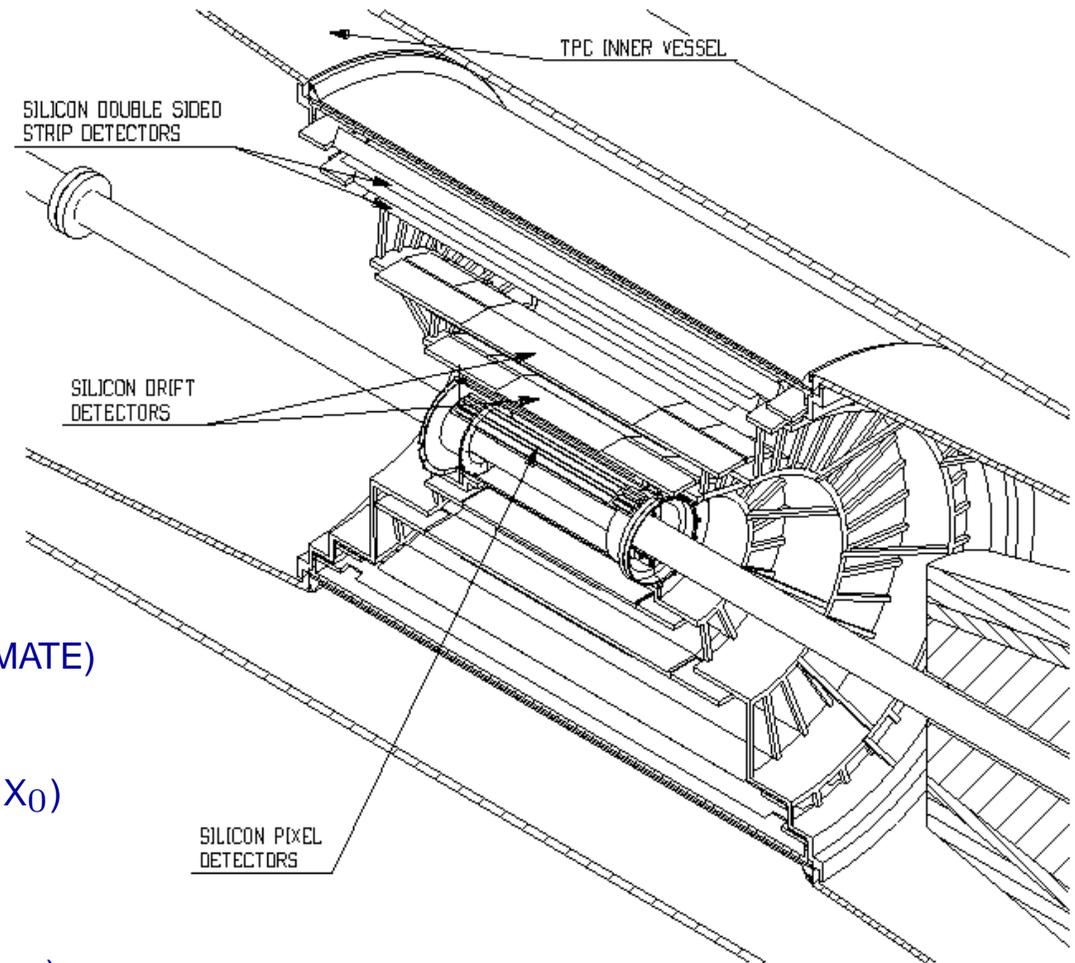


- **Submission expected in 2013/14:**

- ✳ bonus: avoid paving "large" areas with reticule size sensors  $\Rightarrow$  dead zones, material, connectics/complexity
- ✳ synergy with tracker layers and forward disk projects on collider & fixed target experiments
- ✳ 6 sensors will compose a beam telescope at CERN (AIDA project deliverable)
  - ▷ few ns time stamping resolution associated to each hit by TLU (scintillator)

## ● ITS upgrade :

- \* envisioned for "2016" LHC long shutdown
- \* exploits space left by replacement of beam pipe with small radius (19 mm) section
- \* consists (at least) in introducing L0
  - ≡ additional layer at  $\lesssim 25$  mm radius (potentially : replace part of the ITS)
- \* 2 pixel options considered :
  - ◇ Hybrid pixel sensors with reduced material budget
  - ◇ CMOS pixel sensors derived from STAR-PXL (ULTIMATE)
- \* main characteristics of CMOS option :
  - ◇ double-sided ladder derived from PLUME ( $< 0.5 \% X_0$ )
  - ◇  $\lesssim 50 \mu s$  read-out time
  - ◇  $\sim 4 \mu s$  spatial resolution
  - ◇  $> 1$  MRad &  $10^{13} n_{eq}/cm^2$  at  $T = 30^\circ C$  (target values)
    - ↪ move to  $0.18 \mu m$  technology



▷▷▷ **Technical Proposal due for 2011**

- **CMOS sensor technology is mature for high performance vertexing :**

- ✧ well suited for specifications governed granularity, material budget, power consumption, ... (large surfaces ?), ...
- ✧ excellent performance record with beam telescopes (e.g. EUDET project)
- ✧ 1st vertex detector experience will be gained with STAR-PXL, starting data taking in  $\gtrsim 2$  years

- **Next steps :**

- ✧ CBM-MVD : 2013/14 sensor with 40-50  $\mu s$  r.o. time and several MRad  $\oplus 10^{13} n_{eq}/cm^2$ 
  - ↪ could also be an option for the upgrade of ALICE-ITS
- ✧ Large sensors : 2013/14  $\triangleright 5 \times 5 cm^2$  sensors for forward disks (e.g. EIC vertex detector)
  - ↪ will also equip large area telescope of EU-AIDA project
- ✧ Faster 2D sensors (with in-pixel FEE) :  $\geq 2015 \triangleright 1-2 \mu s$  read-out time

- **Full potential of technology far from being exploited :**

- ✧ important 1st step (2011) : move to 0.18  $\mu m$  feature size
- ✧ far future ( $> 5$  years) : multi-tier (3D) sensors using vertical integration